

1/55

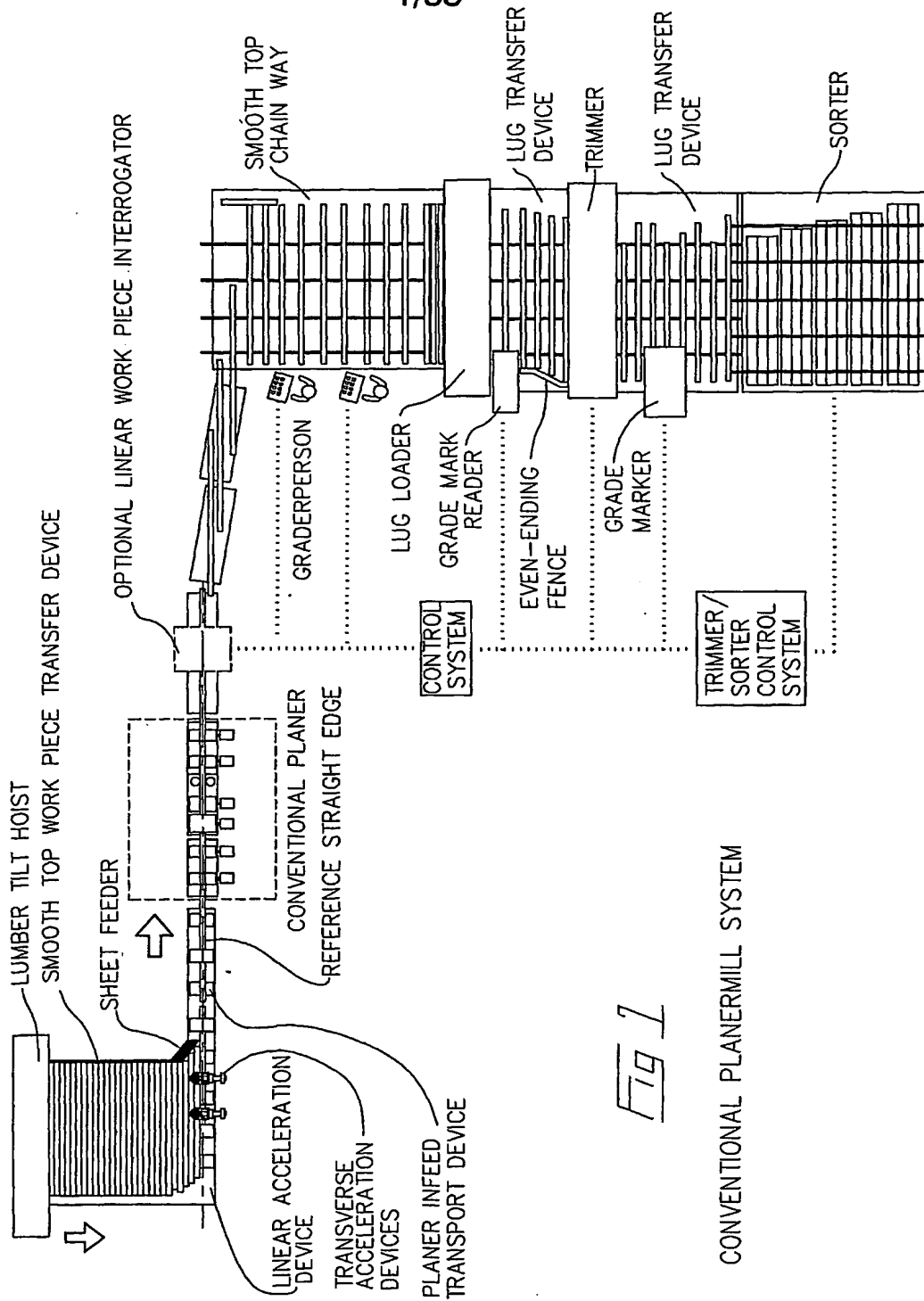
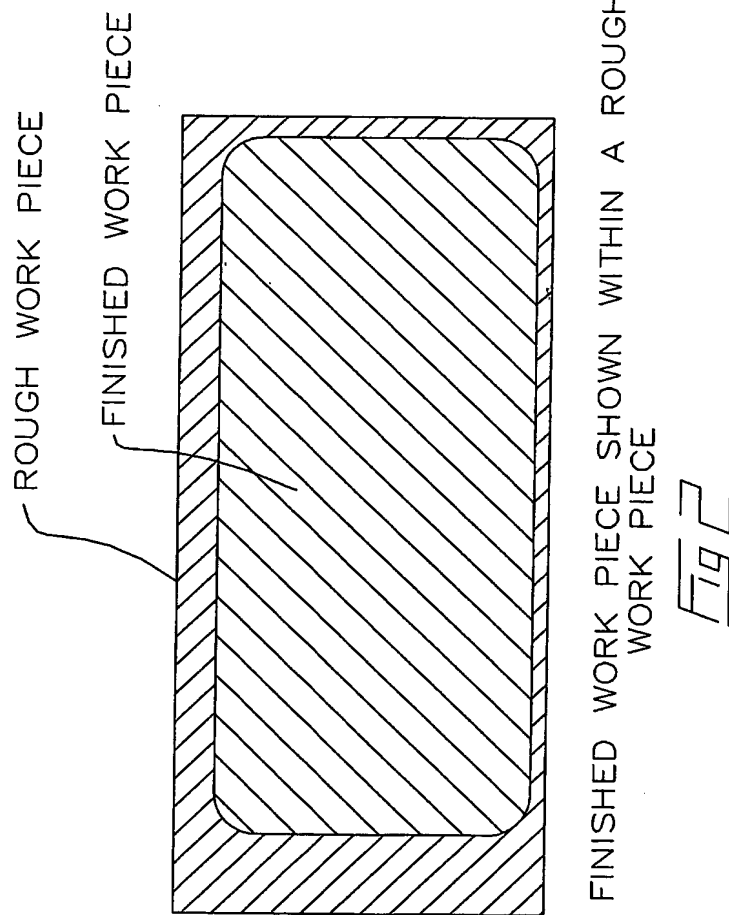


Fig 1

CONVENTIONAL PLANERMILL SYSTEM

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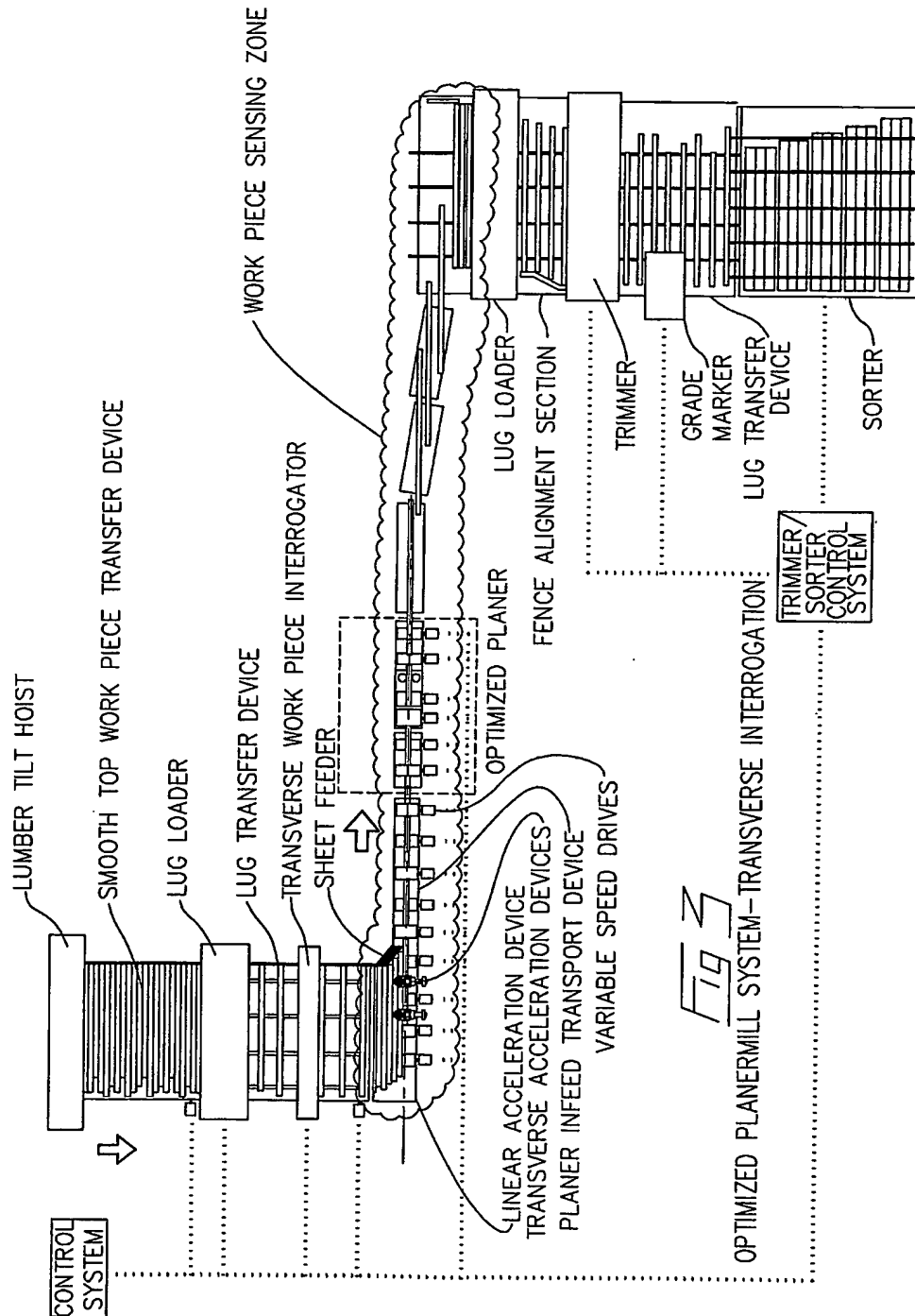


Fig 3

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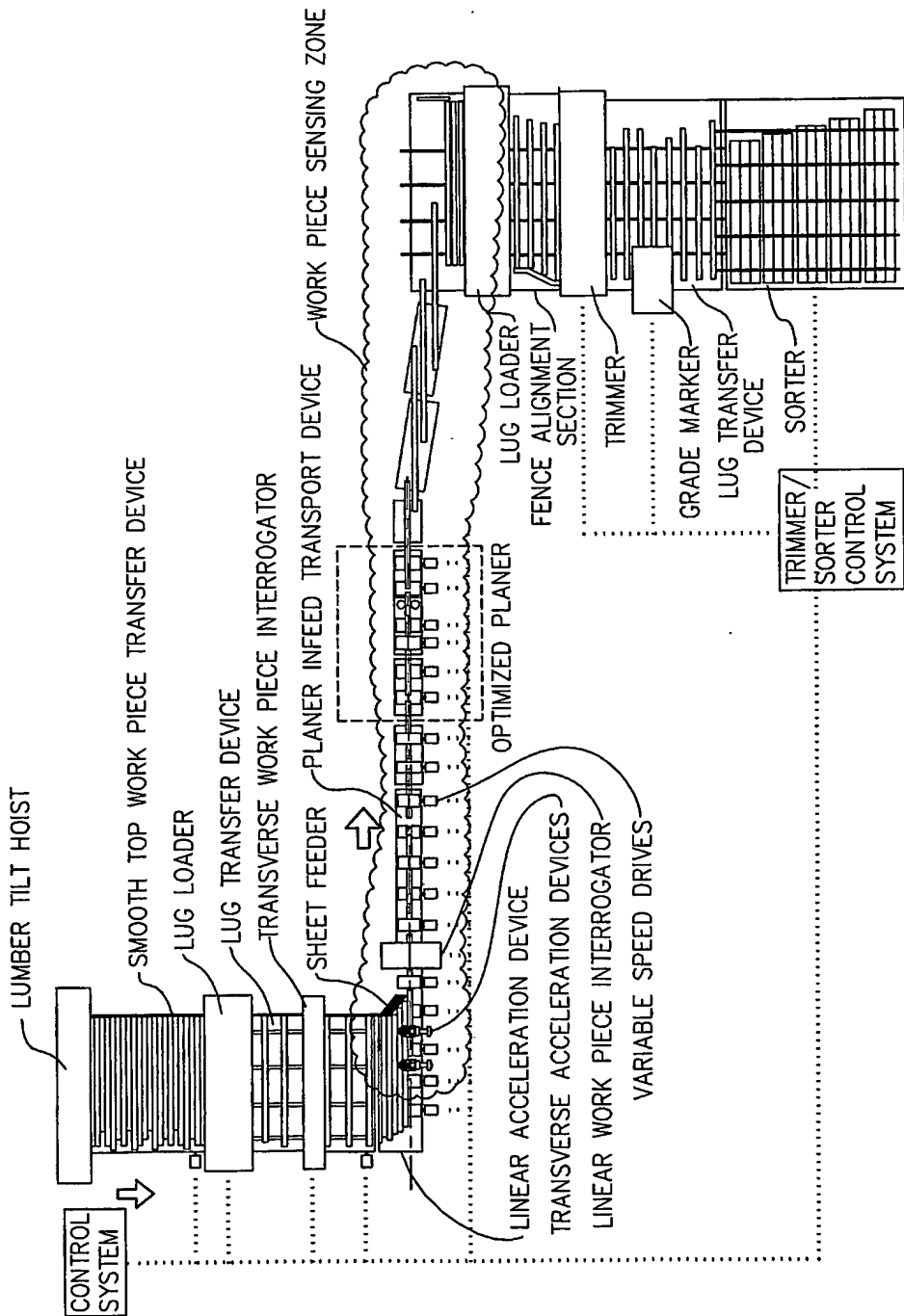
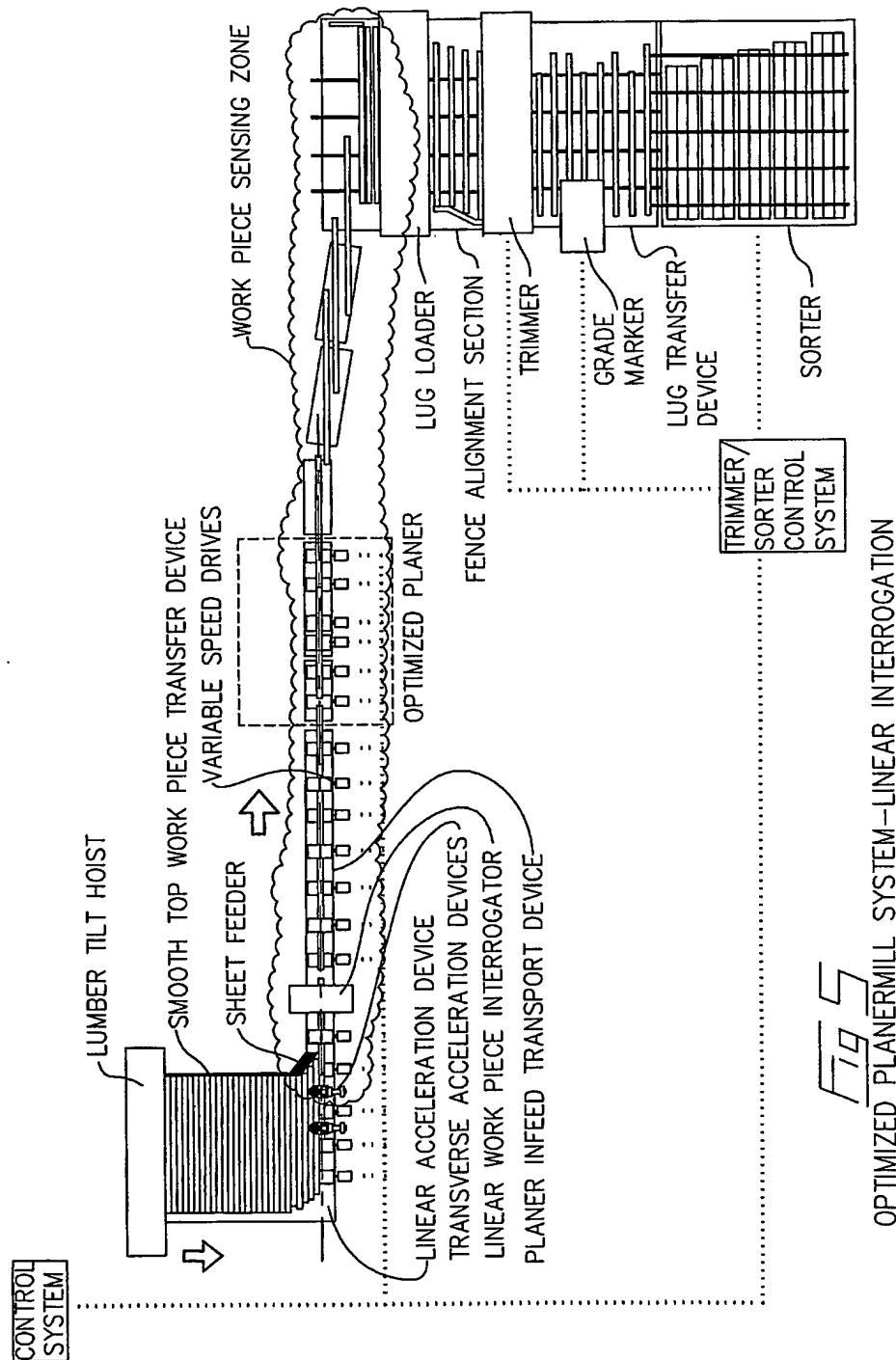


Fig 4

OPTIMIZED PLANERMILL SYSTEM—TRANSVERSE AND LINEAR INTERROGATION

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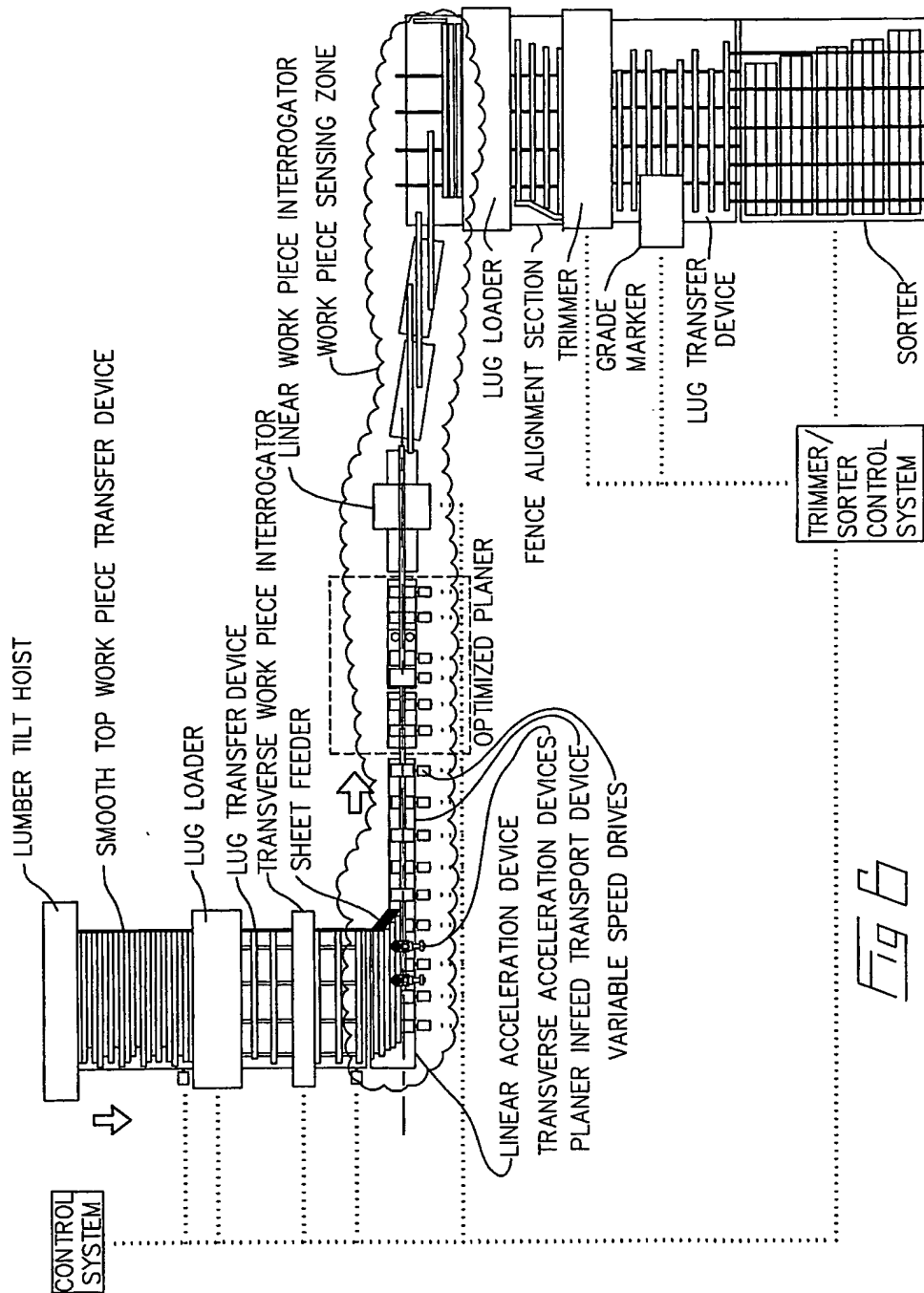


Fig 6

OPTIMIZED PLANERMILL SYSTEM-TRANSVERSE INTERROGATION  
(WITH POST PLANER INTERROGATION)

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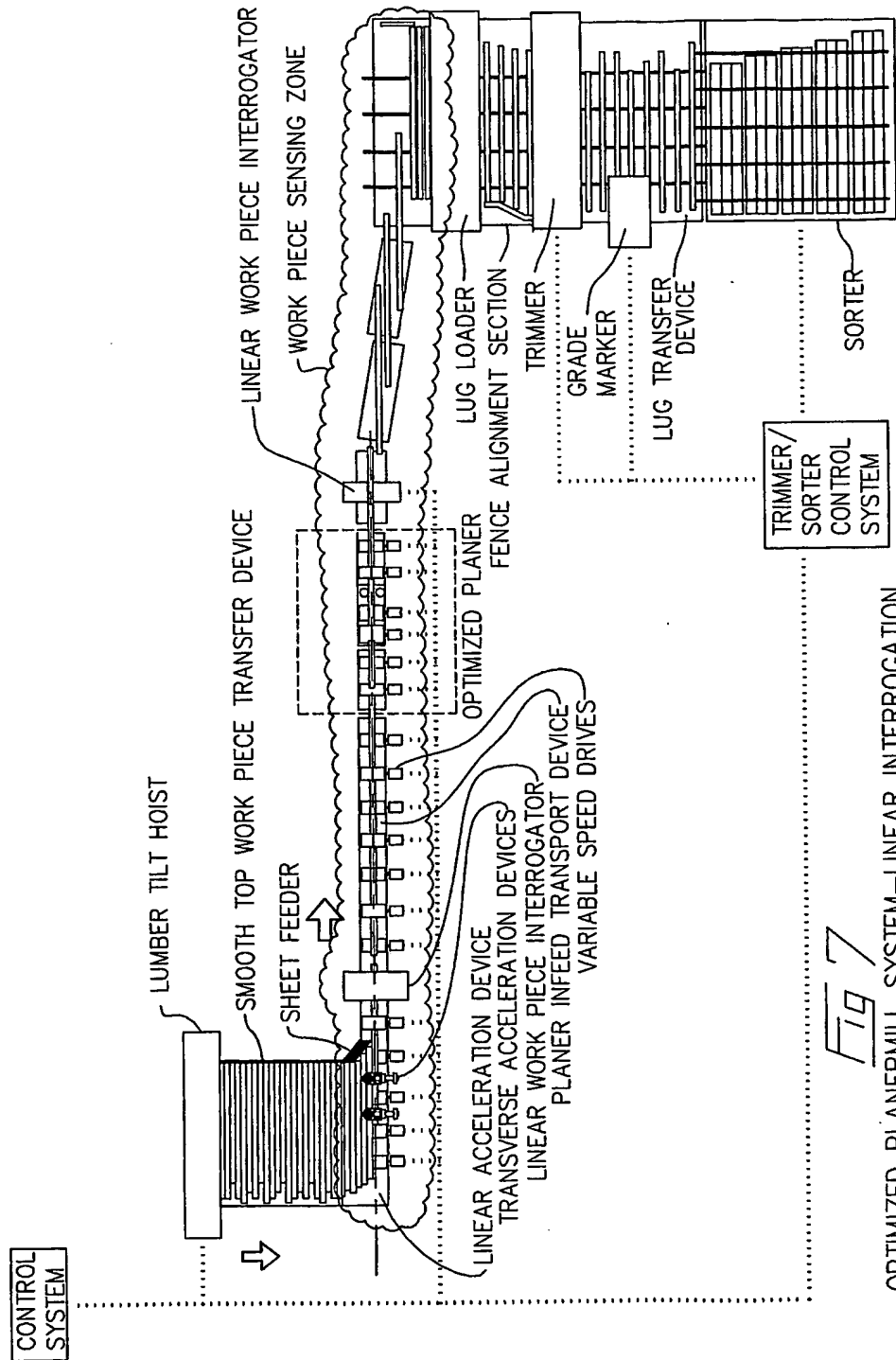
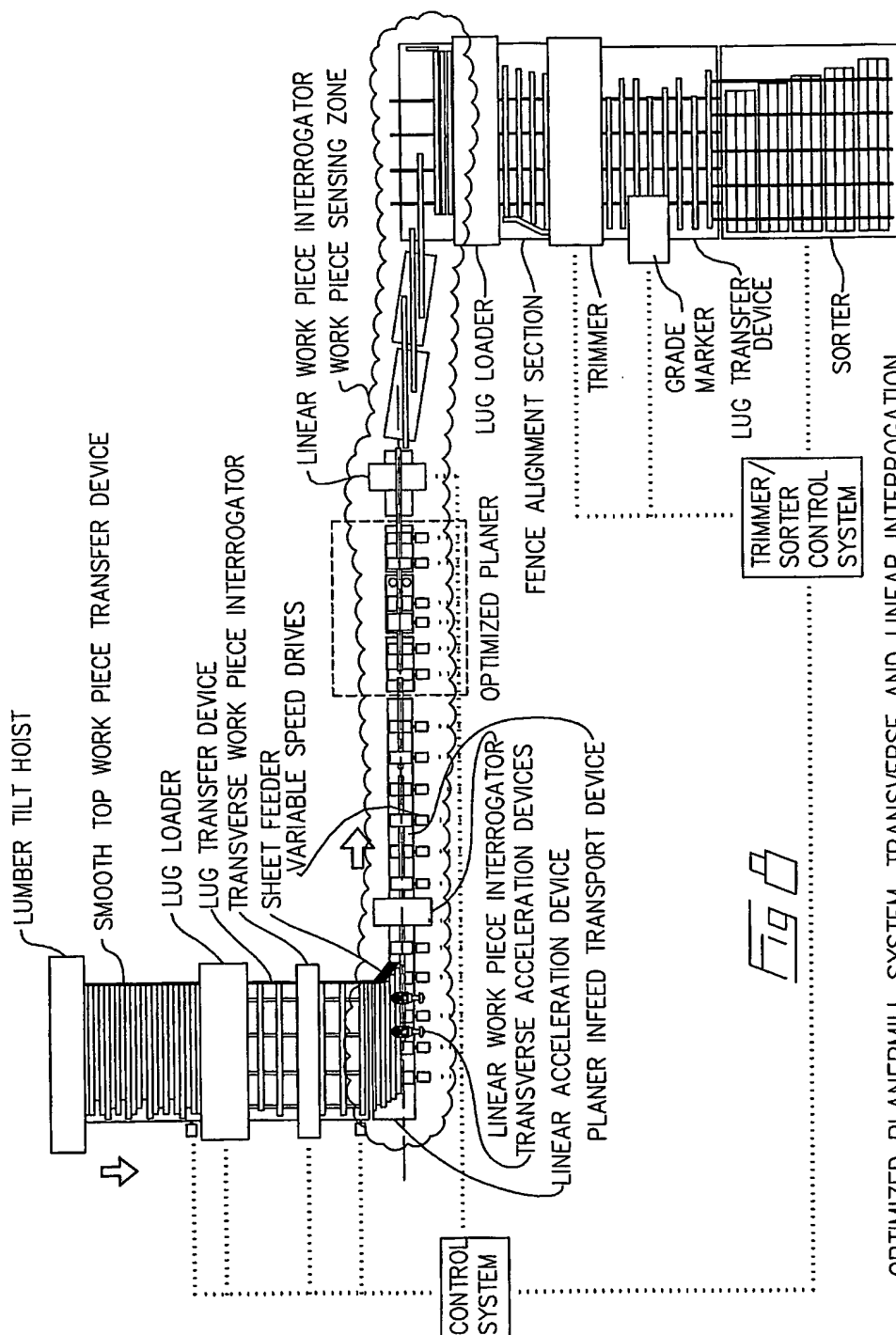


Fig 7  
OPTIMIZED PLANERMILL SYSTEM—LINEAR INTERROGATION  
(WITH POST PLANER INTERROGATION)

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OPTIMIZED PLANERMILL SYSTEM-TRANSVERSE AND LINEAR INTERROGATION  
(WITH POST PLANER INTERROGATION)



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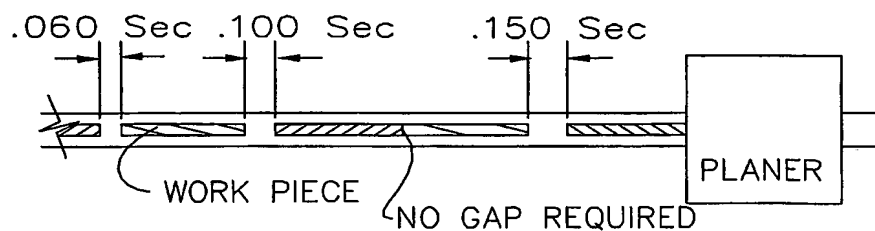


Fig 9

SIMPLIFIED EXAMPLE OF FULLY OPTIMIZED GAP CONTROL

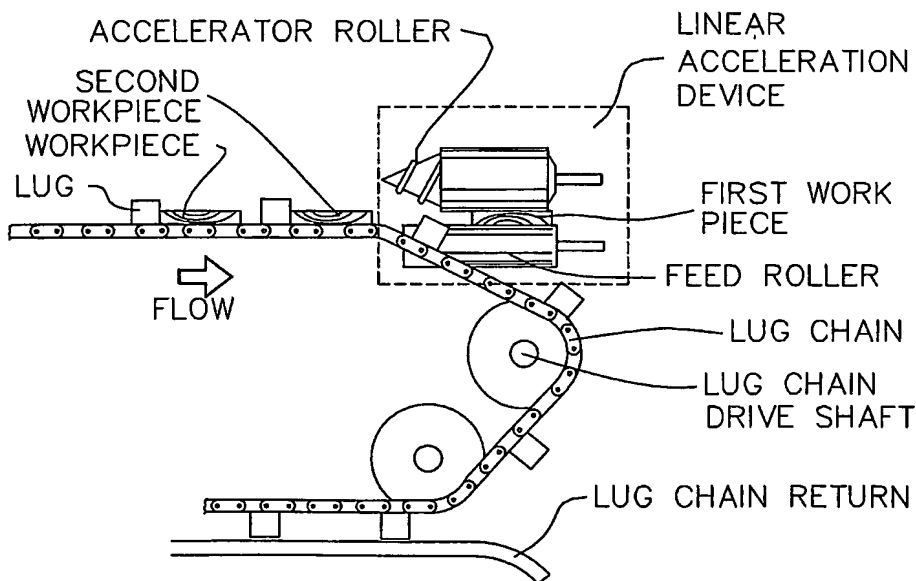
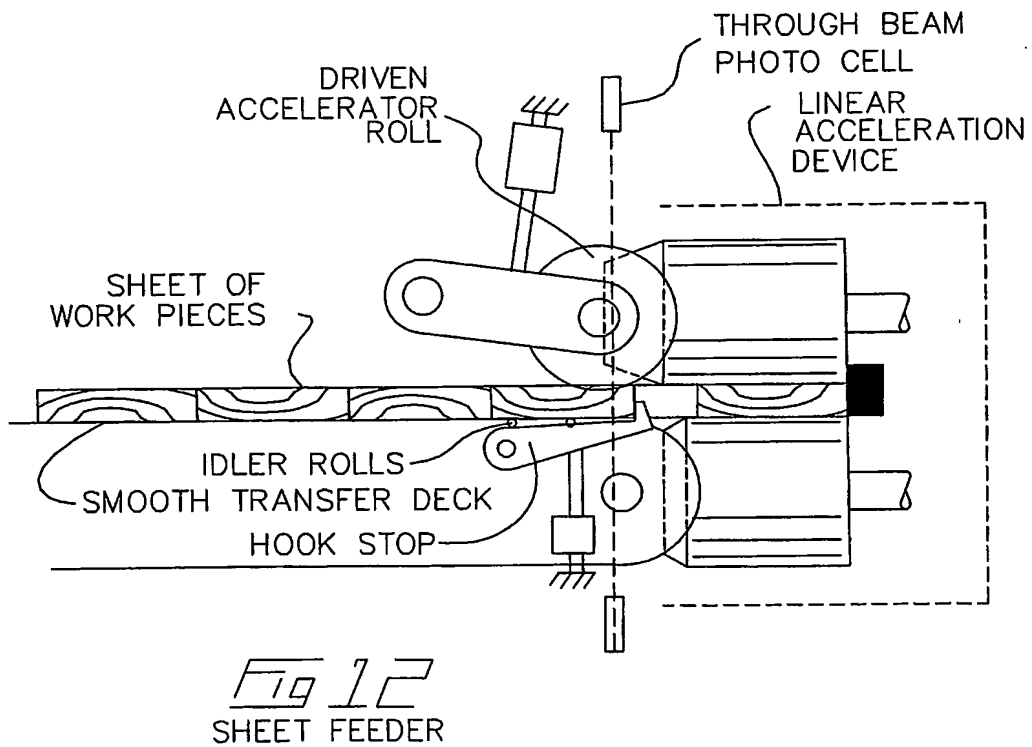
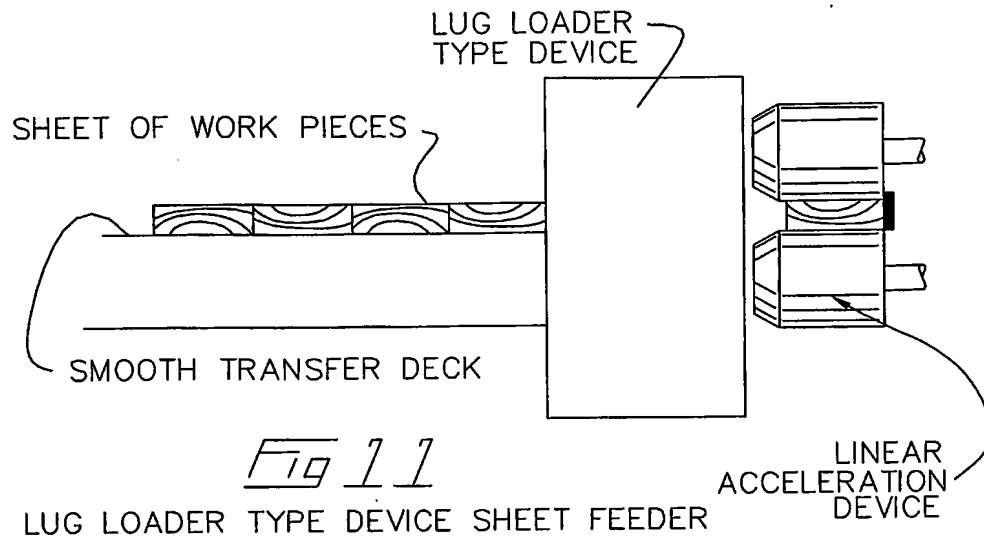


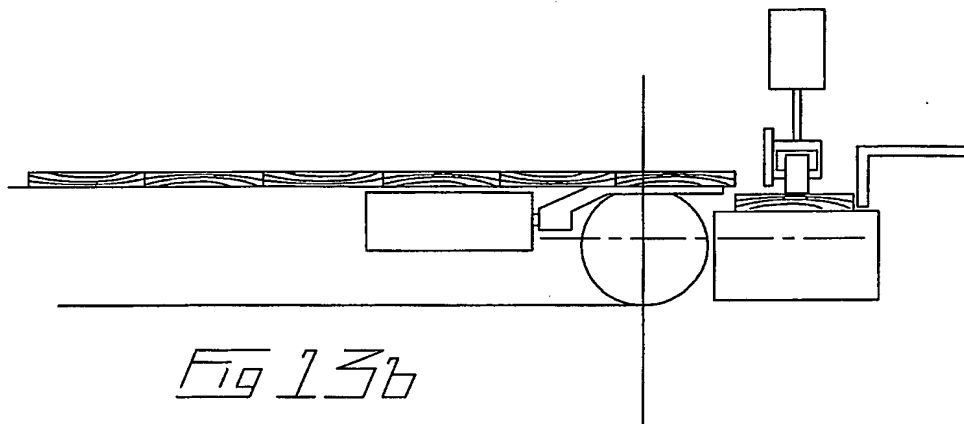
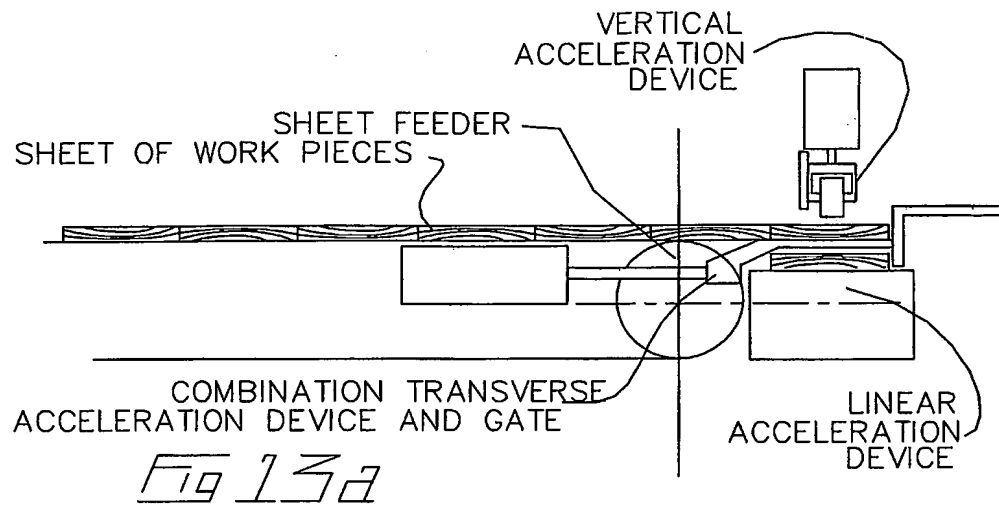
Fig 10

LUG TRANSFER DEVICE FEEDING WORKPIECES  
WITH A LINEAR ACCELERATION DEVICE

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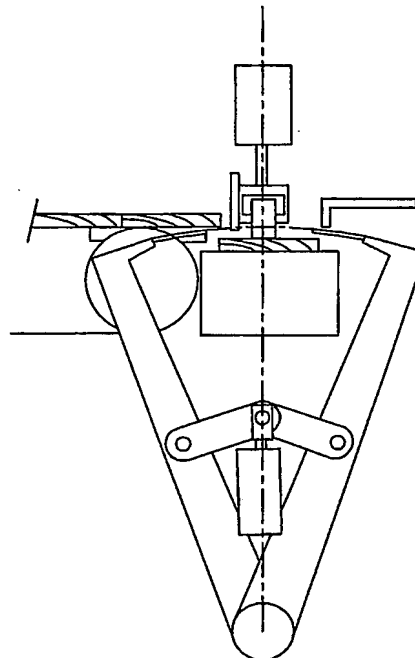
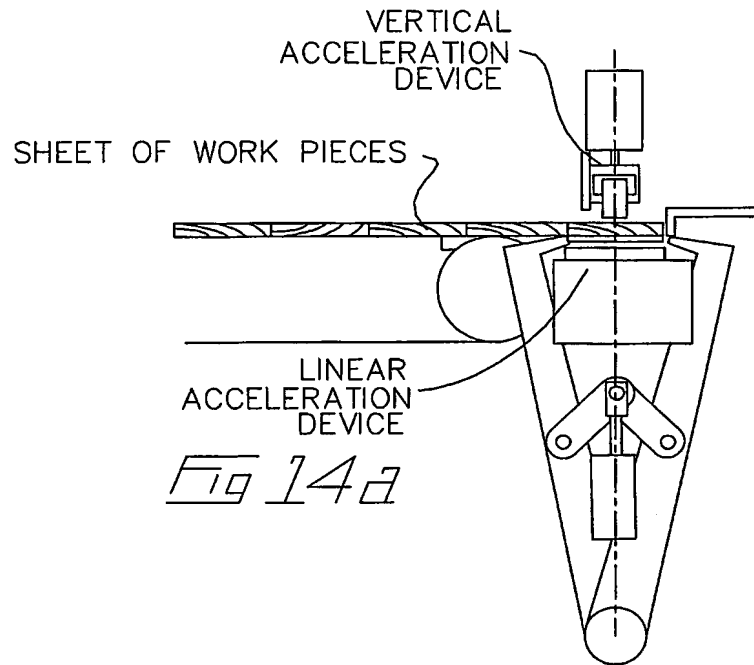


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SHEET FED TRANSVERSE ACCELERATION DEVICE COMBINED WITH  
VERTICAL ACCELERATION DEVICE AND LINEAR ACCELERATION DEVICE

12/55



ALTERNATE SHEET FED VERTICAL ACCELERATION

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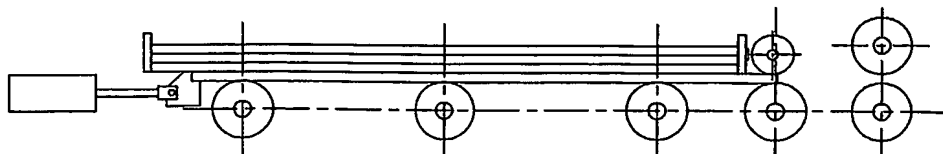
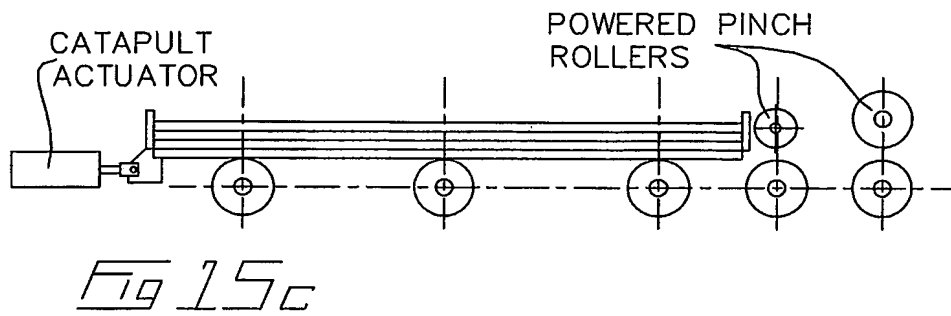
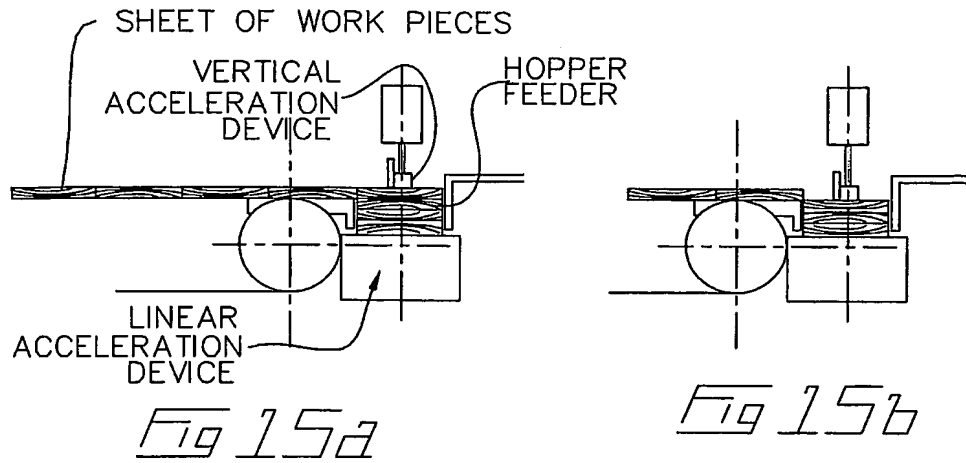
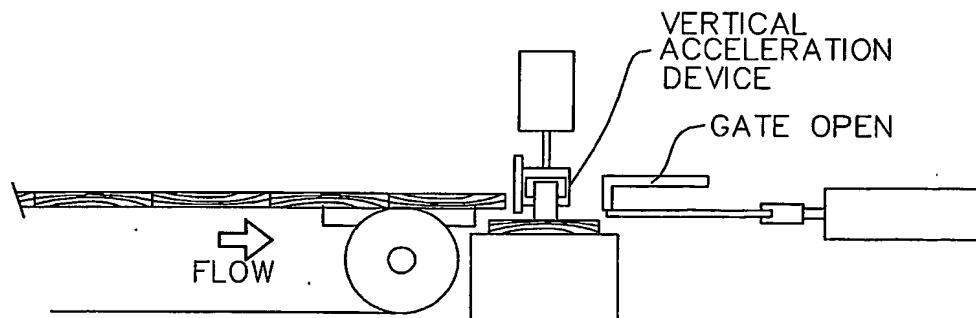
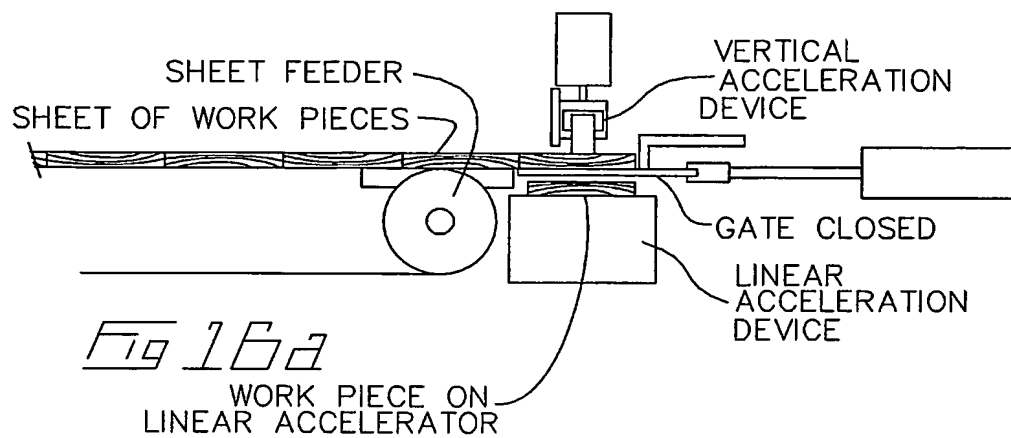
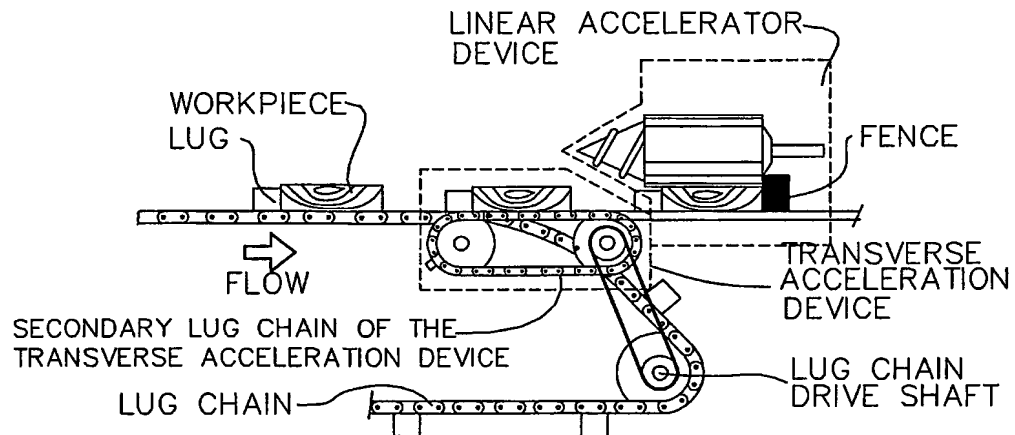


Fig 15d  
SHEET FED HOPPER FEEDER DEVICE

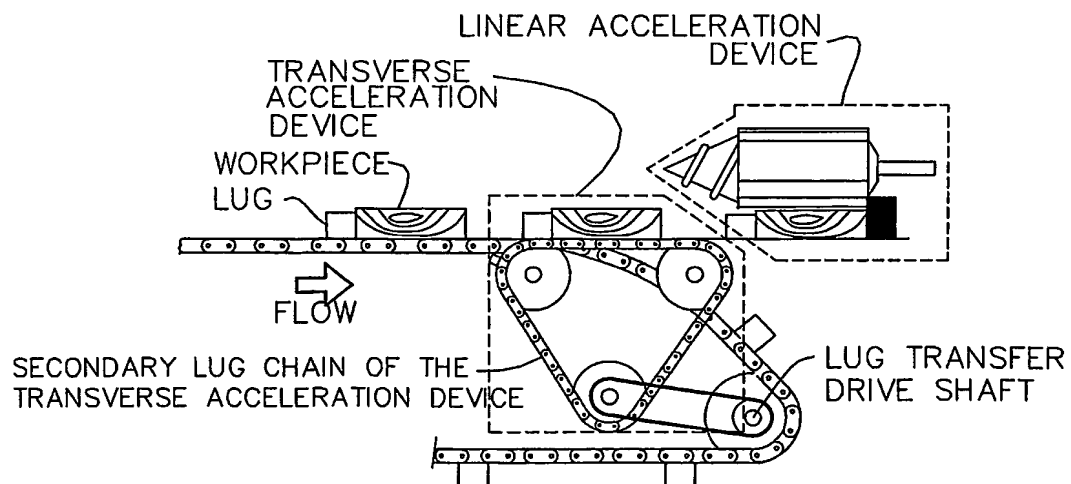
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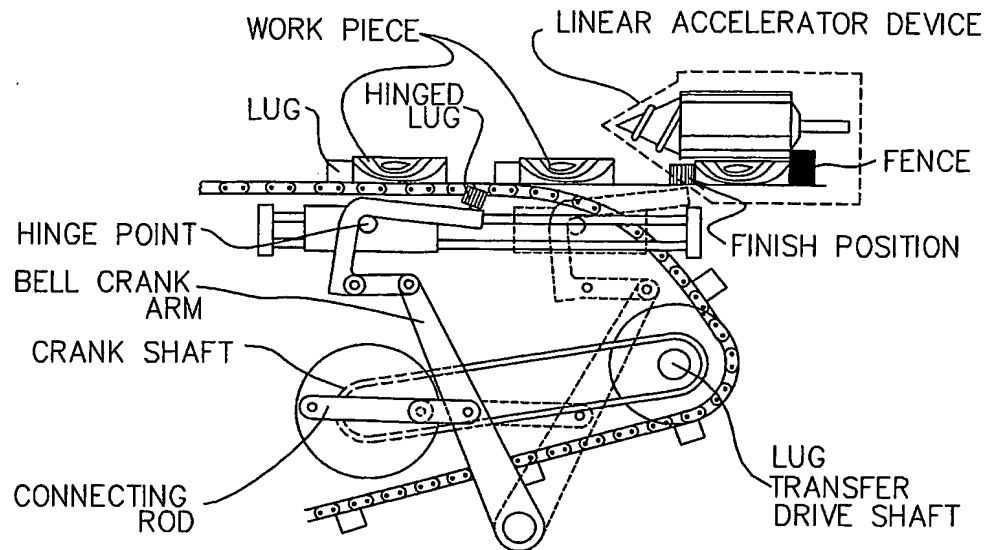


*Fig 17*  
TRANSVERSE ACCELERATION DEVICE  
FEEDING LINEAR ACCELERATION DEVICE

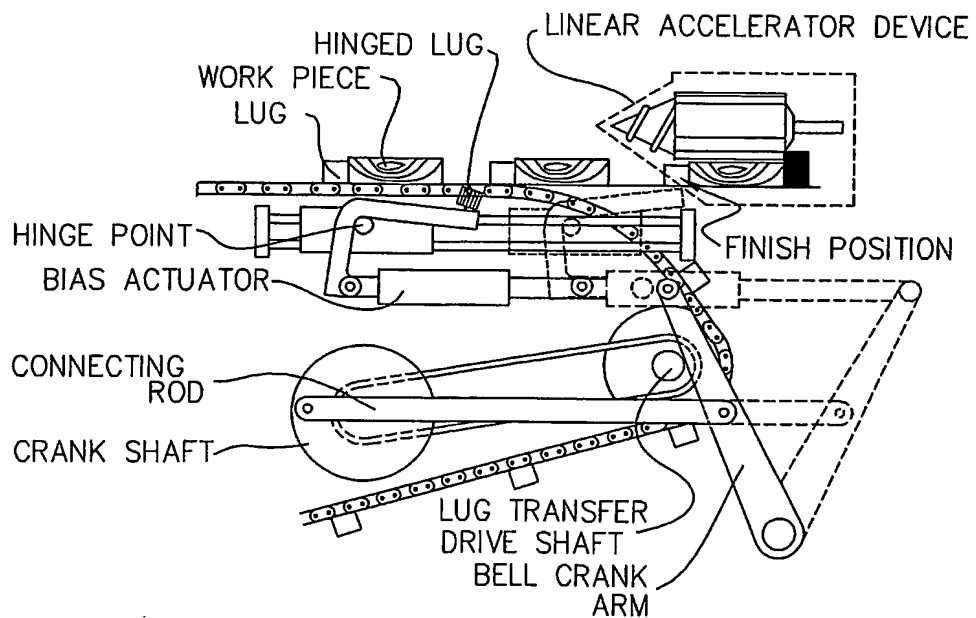


*Fig 18*  
TRANSVERSE ACCELERATION DEVICE  
FEEDING LINEAR ACCELERATION DEVICE

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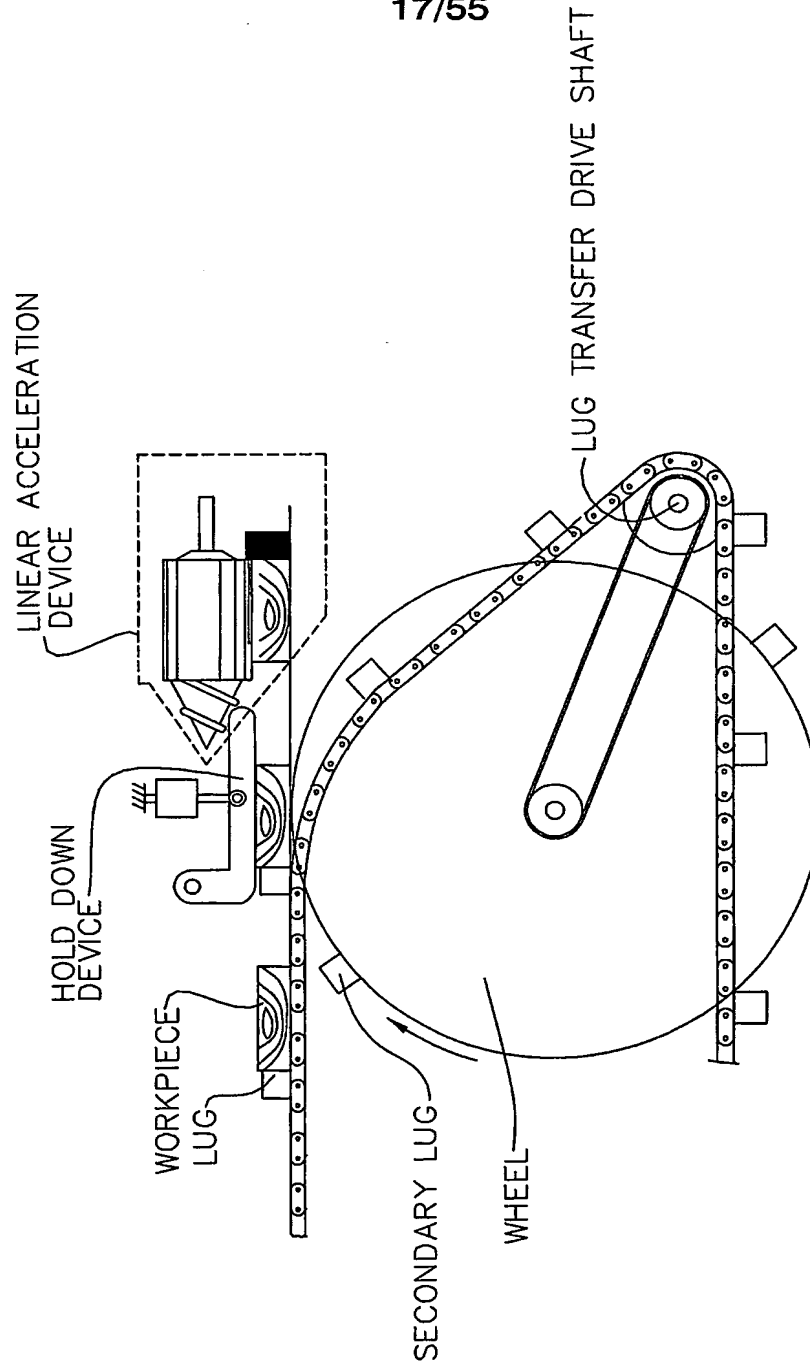
**Fig 19**  
TRANSVERSE ACCELERATION DEVICE  
SLIDER CRANK TYPE



**Fig 20**  
TRANSVERSE ACCELERATION DEVICE



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*Fig 21*

TRANSVERSE ACCELERATION DEVICE

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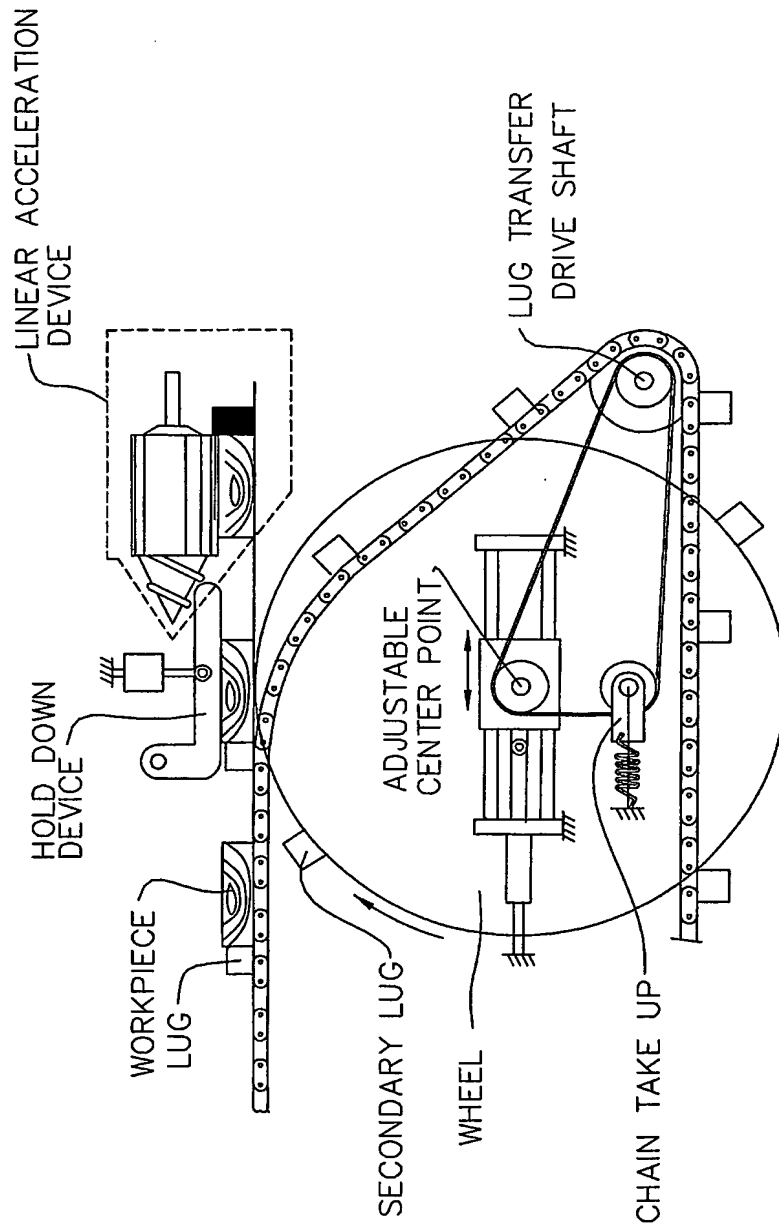


Fig 22

TRANSVERSE ACCELERATION DEVICE

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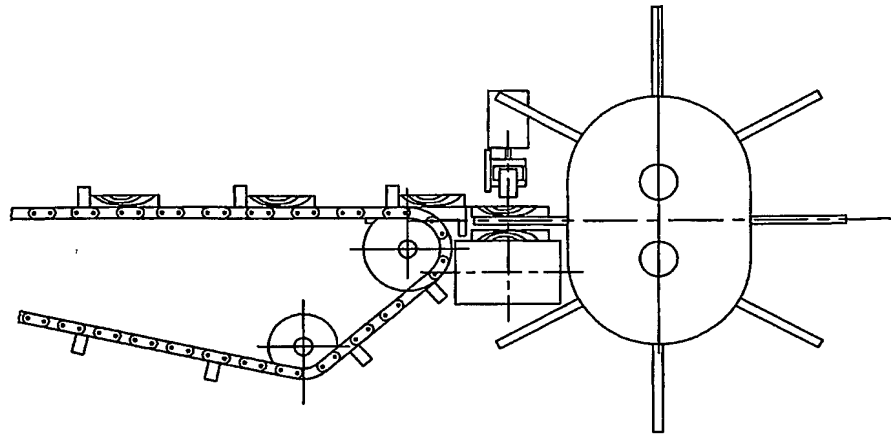


Fig 23a

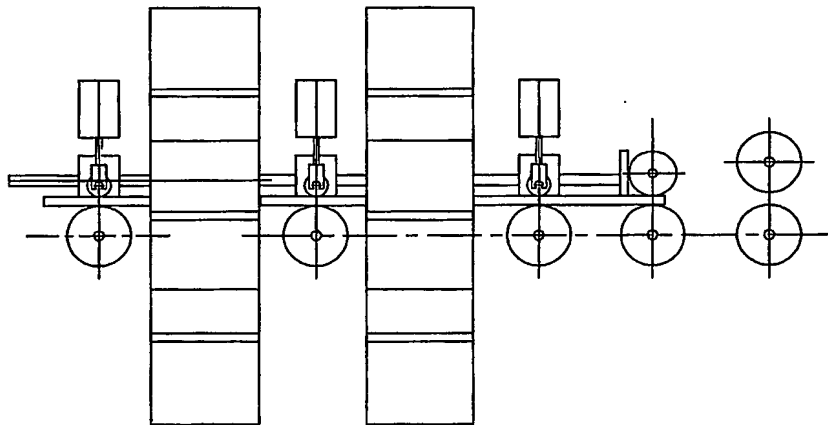


Fig 23b

CONTINUOUS INDEXIBLE SUPPORT ARM  
VERTICAL ACCELERATION DEVICE

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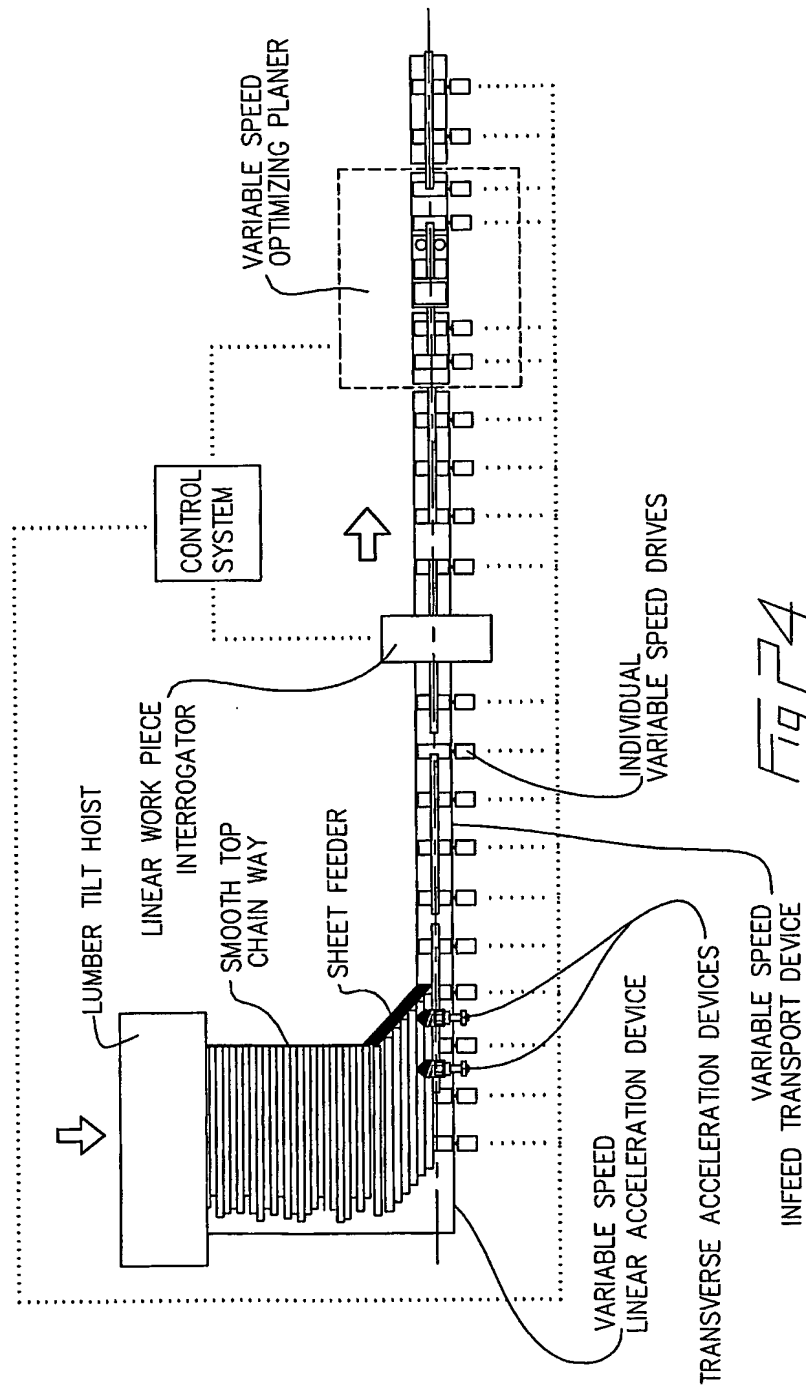


Fig 24

VARIABLE SPEED INFEED TRANSPORT DEVICE WITH A SHEET FED LINEAR ACCELERATOR DEVICE AND A LINEAR WORK PIECE INTERROGATOR

21/55

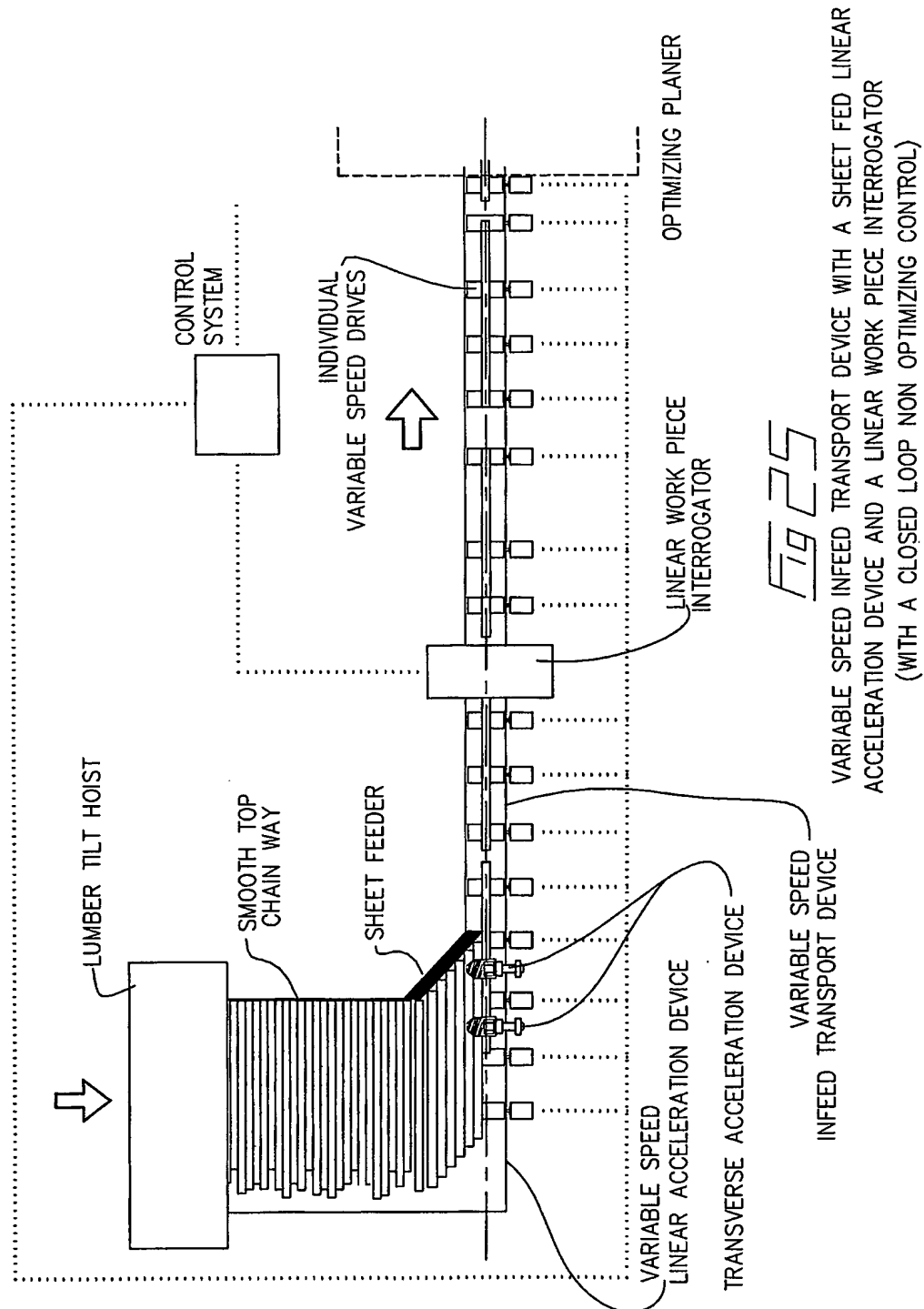
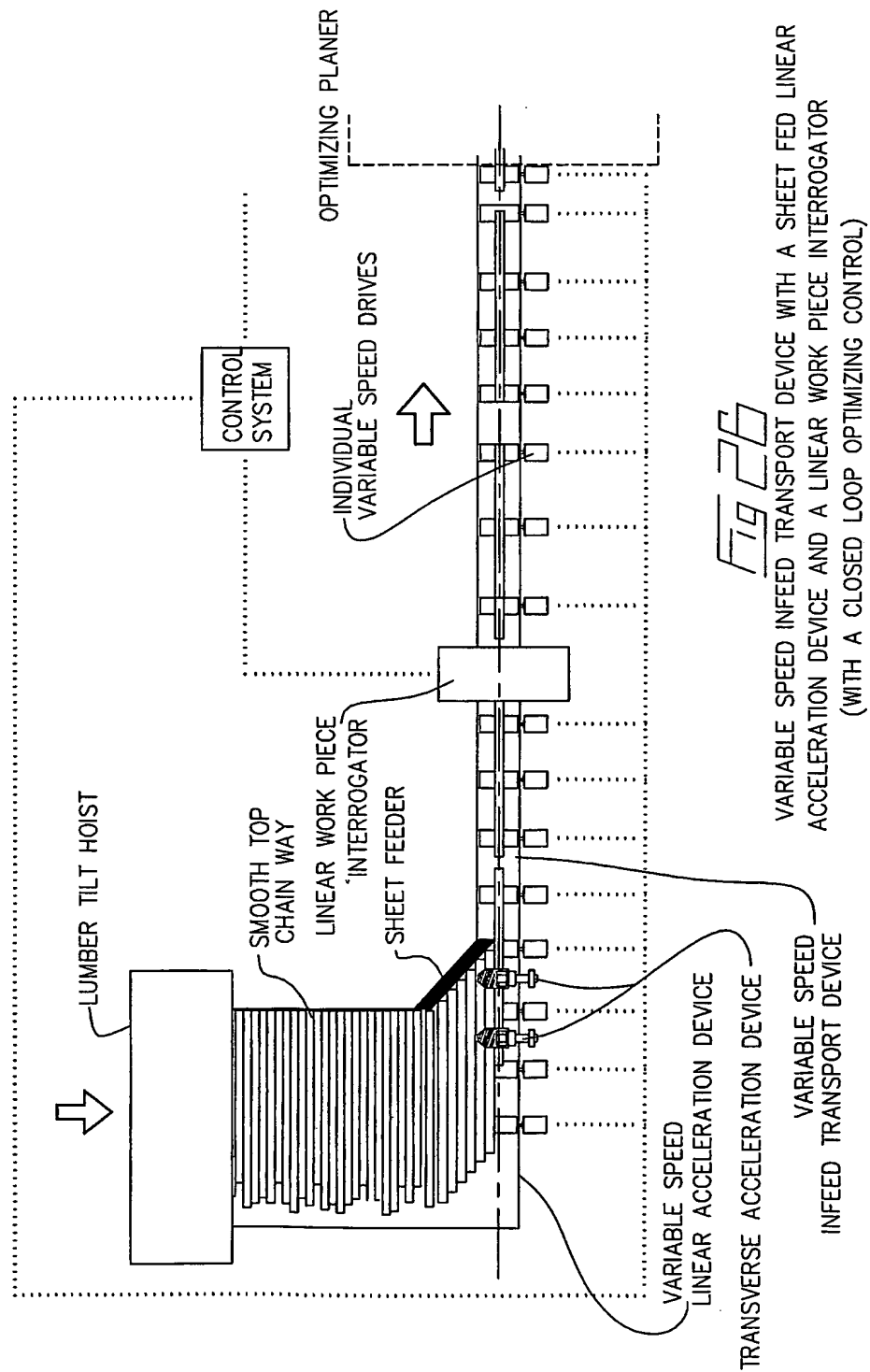


Fig 25

VARIABLE SPEED INFEED TRANSPORT DEVICE WITH A SHEET FED LINEAR ACCELERATION DEVICE AND A LINEAR WORK PIECE INTERROGATOR (WITH A CLOSED LOOP NON OPTIMIZING CONTROL)

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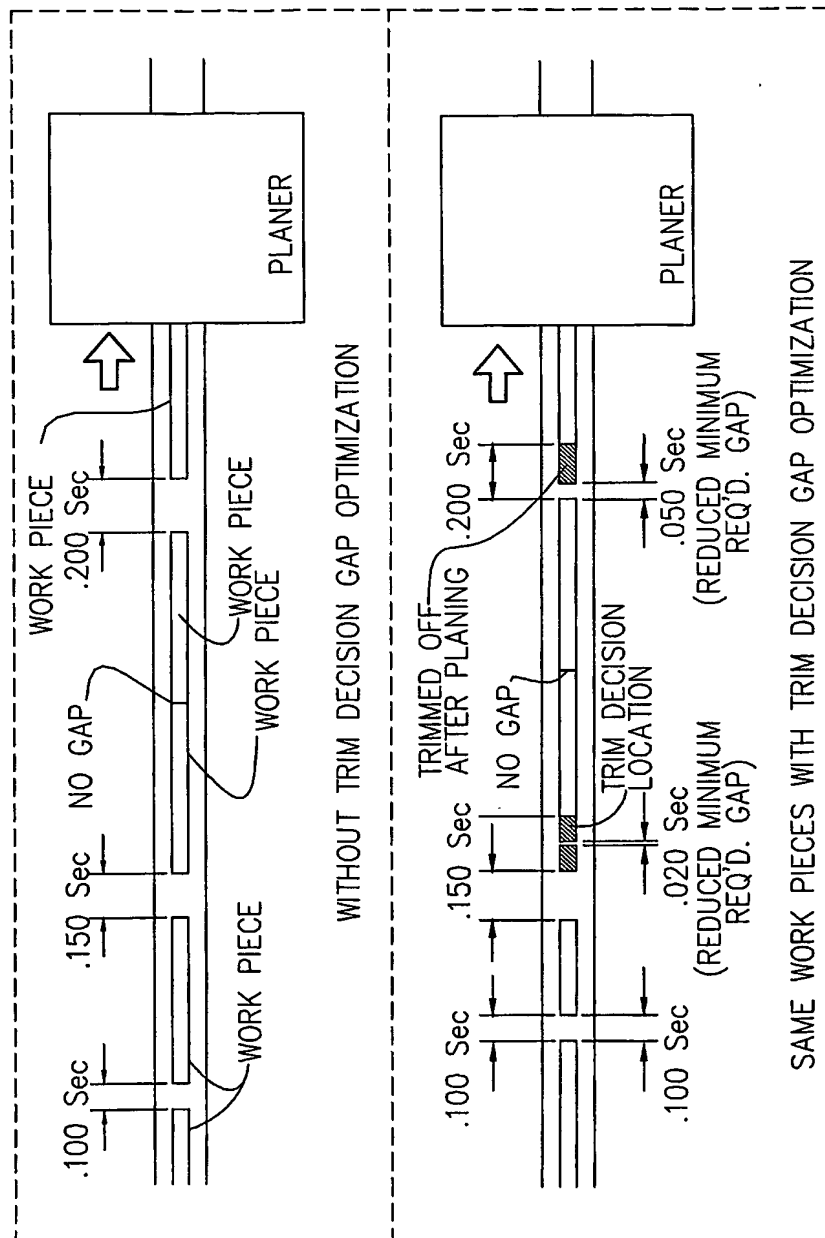


Fig 27

EXAMPLE OF FULLY OPTIMIZED GAP CONTROL  
(WITH AND WITHOUT THE ADDITION OF TRIM DECISION GAP OPTIMIZATION)

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		SHEET FEEDER	FIXED SPEED LUG TRANSFER	VARIABLE SPEED LUG TRANSFER	FIXED SPEED TAD	VARIABLE SPEED TAD	VERTICAL AD	FIXED SPEED LAD	VARIABLE SPEED LAD	FIXED SPEED ITD	VARIABLE SPEED ITD	FIXED SPEED PLANNER	VARIABLE SPEED PLANNER	LINEAR WPI	TRANSVERSE WPI	WPS	OLNO	CLNO	CLO
1	A	X																	
2	X																		
3	X																		
4	X																		
5	X																		
6	X																		
7	X																		
8	X																		
9	X																		
10	X																		
11	X																		
12	X																		
13	X																		
14	X																		
15	X																		
16	X																		
17	X																		
18	X																		
19	X																		
20	X																		
21	X																		
22	X																		
23	X	X																	
24	X	X																	
25	X	X																	
26	X	X																	
27	X	X																	
28		X																	
29		X																	
30		X																	
31		X																	
32		X																	
33		X																	
34			X																
35			X																
36			X																
37			X																
38			X																
39			X																
40			X																
41			X																
42			X																
43			X																
44			X																

Fig 28



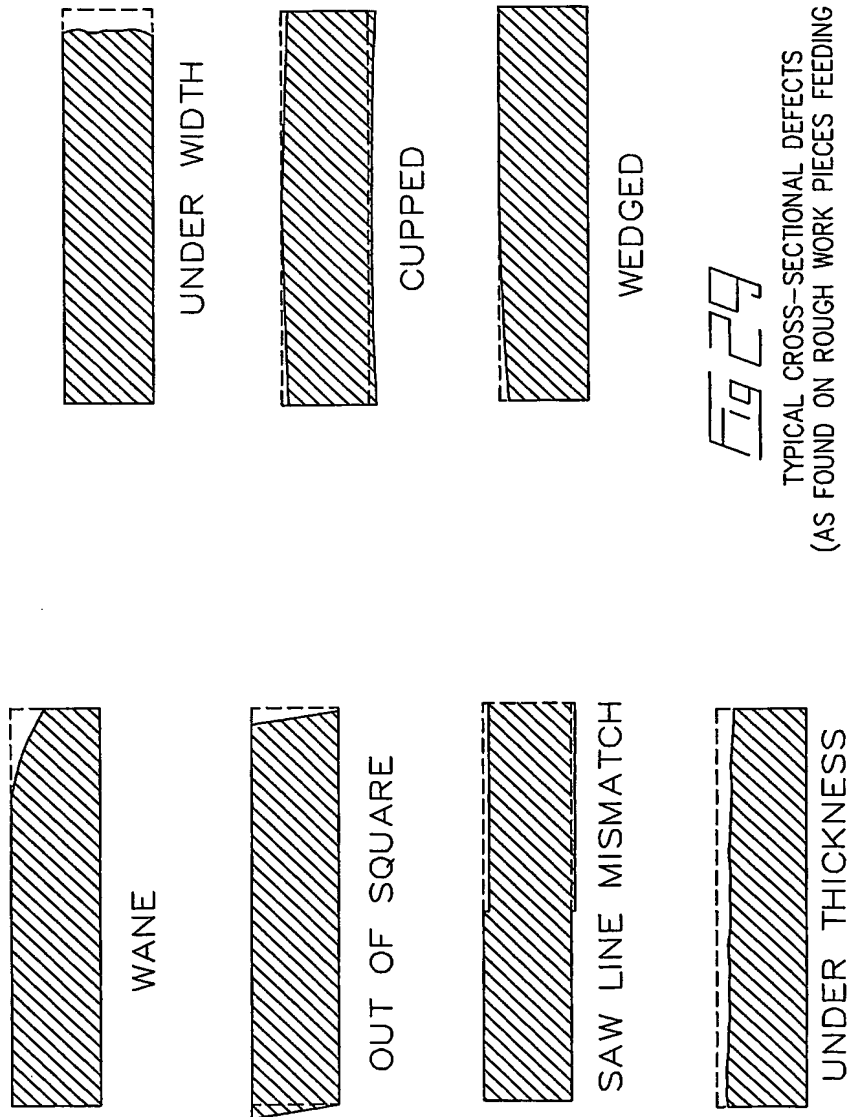
25/55

CONTINUATION OF

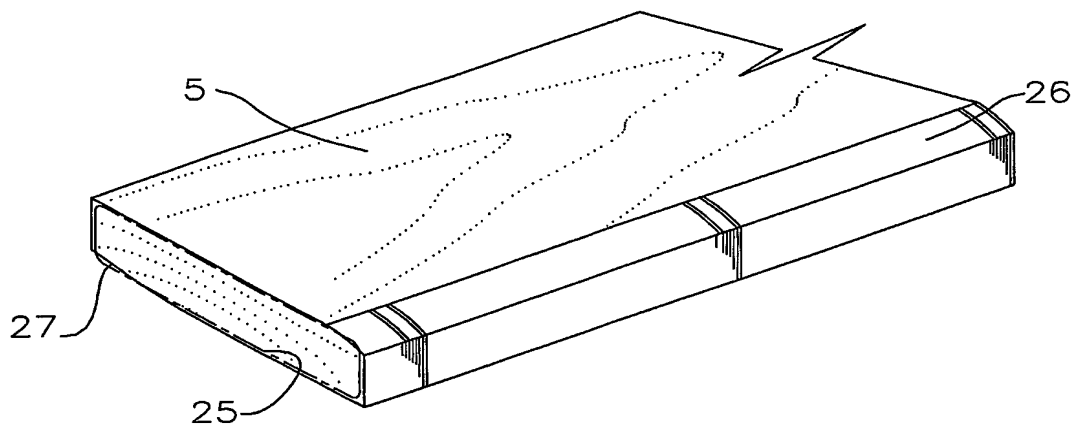
Fig 28

	SHEET FEEDER	FIXED SPEED LUG TRANSFER	VARIABLE SPEED LUG TRANSFER	FIXED SPEED TAD	VARIABLE SPEED TAD	VERTICAL AD	FIXED SPEED LAD	VARIABLE SPEED LAD	FIXED SPEED ITD	VARIABLE SPEED ITD	FIXED SPEED PLANER	VARIABLE SPEED PLANER	LINEAR WPI	TRANSVERSE WPI	WPS	OLNO	CLNO	CLO
	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R
45			X				X			X		X		X	X		X	X
46			X	X				X	X		X			X	X		X	
47			X	X				X	X		X			X	X			X
48			X	X				X	X		X			X	X		X	
49			X	X				X	X		X			X	X			X
50			X	X				X				X		X	X		X	
51			X	X				X				X		X	X			X
52			X		X		X		X		X			X	X		X	
53			X		X		X		X		X			X	X		X	X
54			X		X			X	X		X			X	X		X	
55			X		X			X	X		X			X	X		X	X
56			X		X			X	X		X			X	X		X	X
57			X		X			X		X				X	X		X	X
58			X		X			X		X		X		X	X		X	
59			X		X			X		X		X		X	X			X
60		X				X	X				X			X		X		
61		X				X	X		X		X			X				
62		X				X	X			X	X			X	X		X	
63		X				X		X		X	X			X	X		X	
64		X				X		X		X	X			X	X		X	X
65		X				X		X		X		X		X	X		X	
66		X				X		X		X		X		X	X			X
67			X			X	X				X			X	X		X	X
68			X			X	X				X			X	X			X
69			X			X	X		X		X			X	X		X	
70			X			X	X		X		X			X	X			X
71			X			X		X	X		X			X	X		X	
72			X			X		X	X		X			X	X		X	X
73			X			X		X		X	X			X	X		X	
74			X			X		X		X	X			X	X			X
75			X			X		X		X		X		X	X		X	
76			X			X		X		X		X		X	X			X
77			X			X	X			X		X		X	X		X	
78			X			X	X			X		X		X	X			X
79			X			X			X			X		X	X		X	
80			X			X			X			X		X	X		X	X
81			X			X	X			X	X			X	X		X	
82			X			X	X			X	X			X	X			X
83			X	X			X		X		X		X		X		X	
84			X	X			X			X	X		X		X		X	X
85			X	X			X			X	X		X		X		X	
86			X		X		X			X	X		X		X		X	
87			X		X		X			X	X		X		X			X
88			X		X			X			X		X		X			X

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NON-OPTIMIZED PLANING OF A WORK PIECE

Fig 30

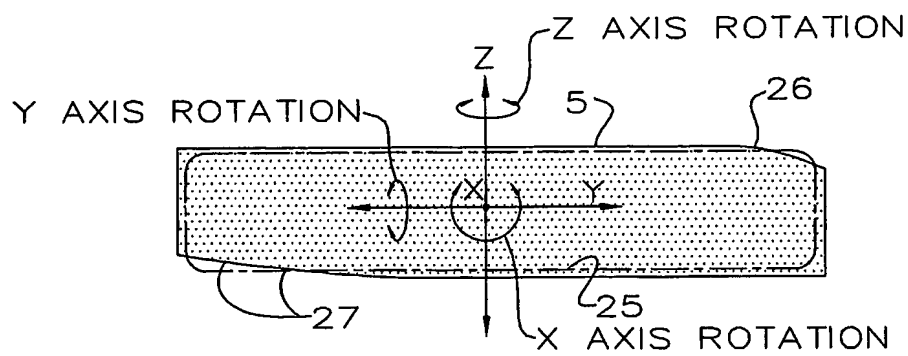
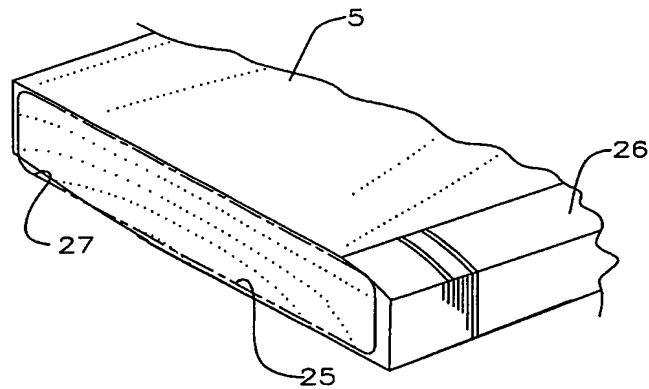


Fig 31

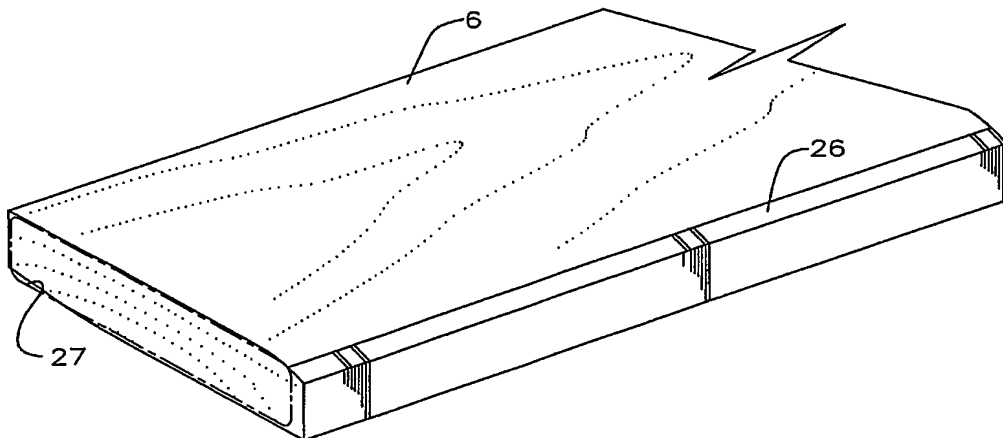
NON-OPTIMIZED PLANING OF A WORK PIECE

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NON-OPTIMIZED PLANING OF A WORK PIECE

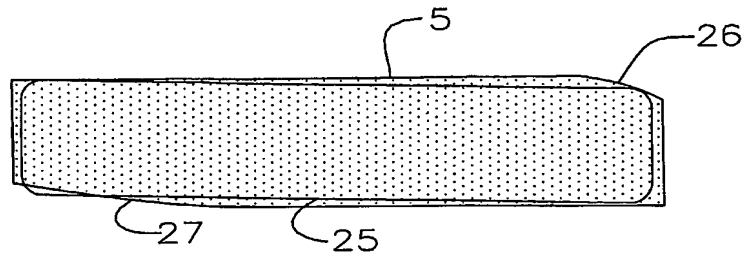
*Fig 32*



NON-OPTIMIZED PLANING OF A WORK PIECE

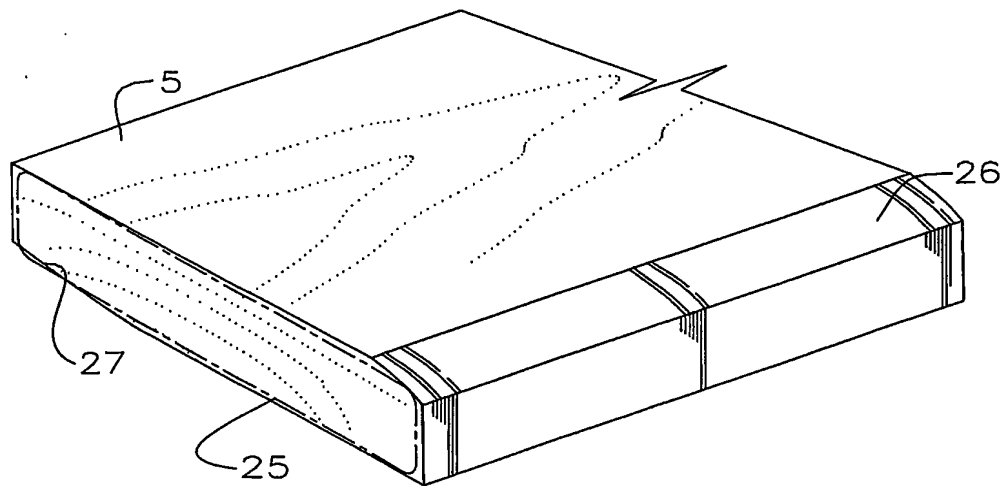
*Fig 33*

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OPTIMIZED PLANING OF A WORK PIECE

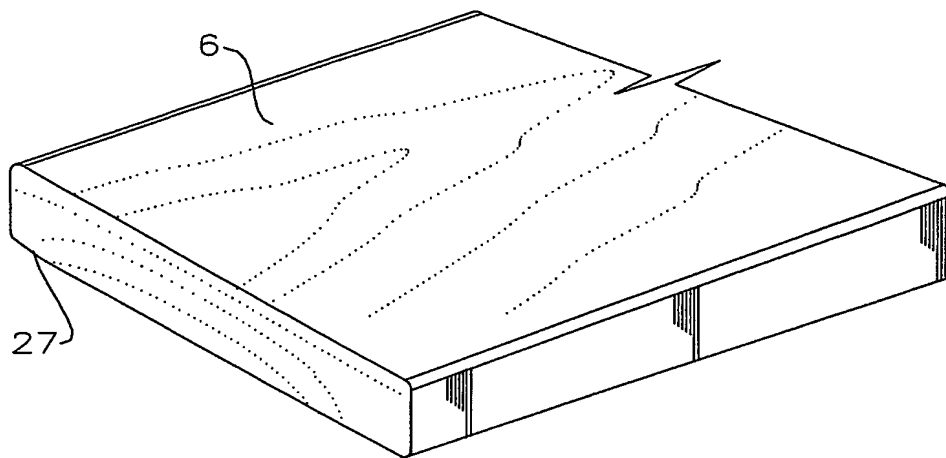
*Fig 34*



OPTIMIZED PLANING OF A WORK PIECE

*Fig 35*

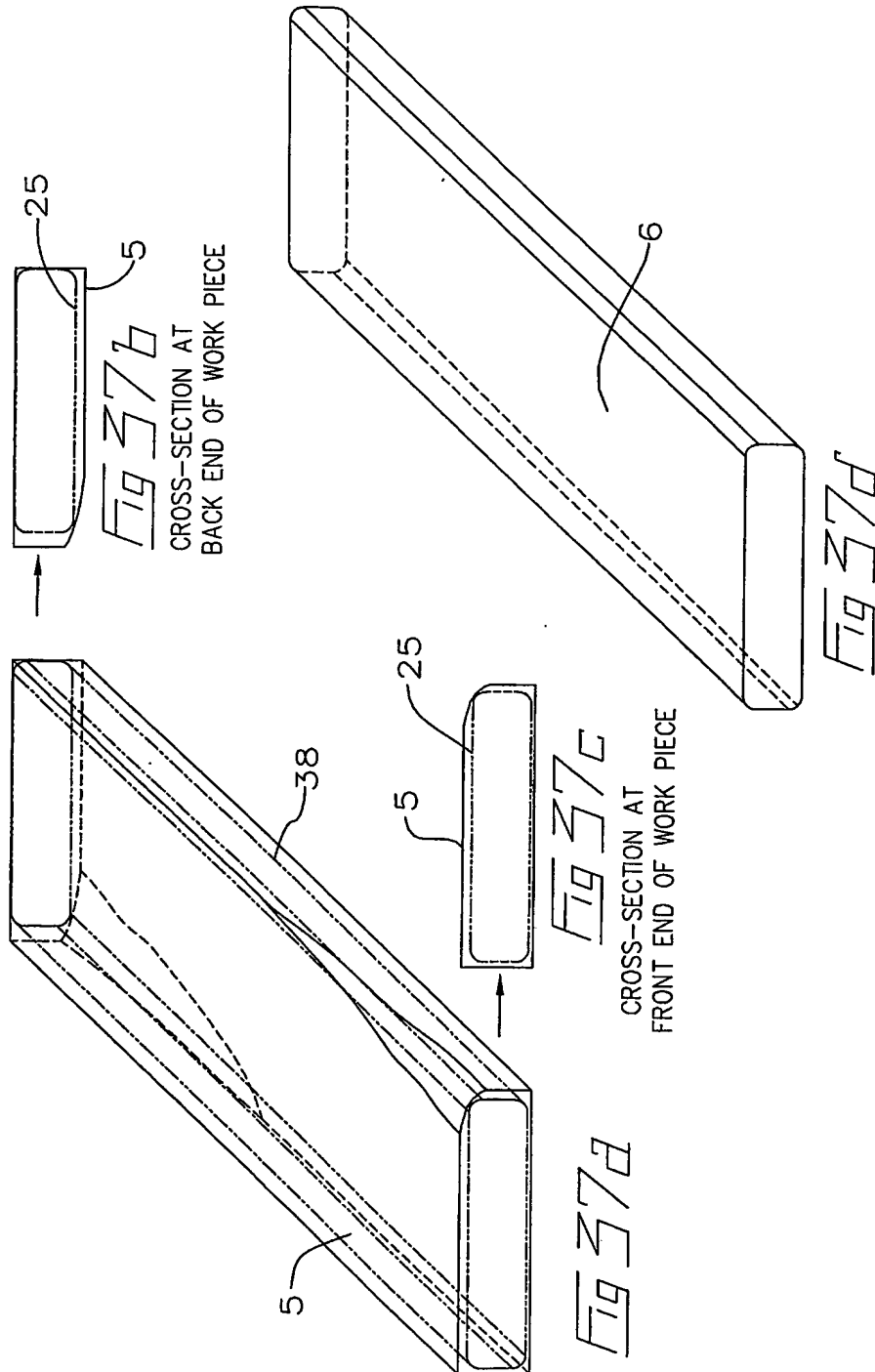
30/55



OPTIMIZED PLANING OF A WORK PIECE

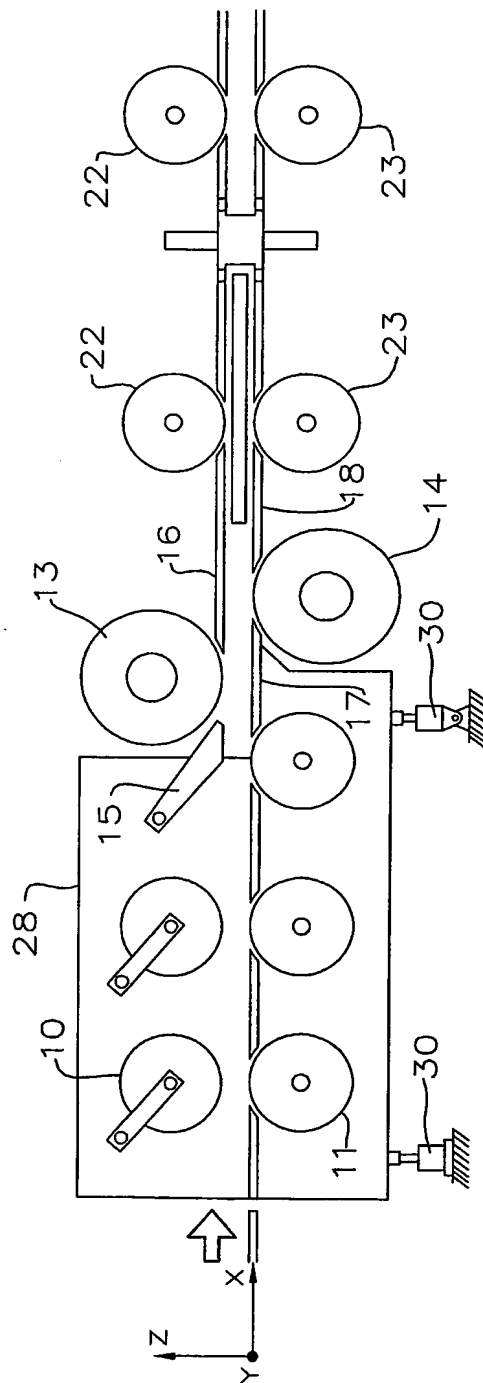
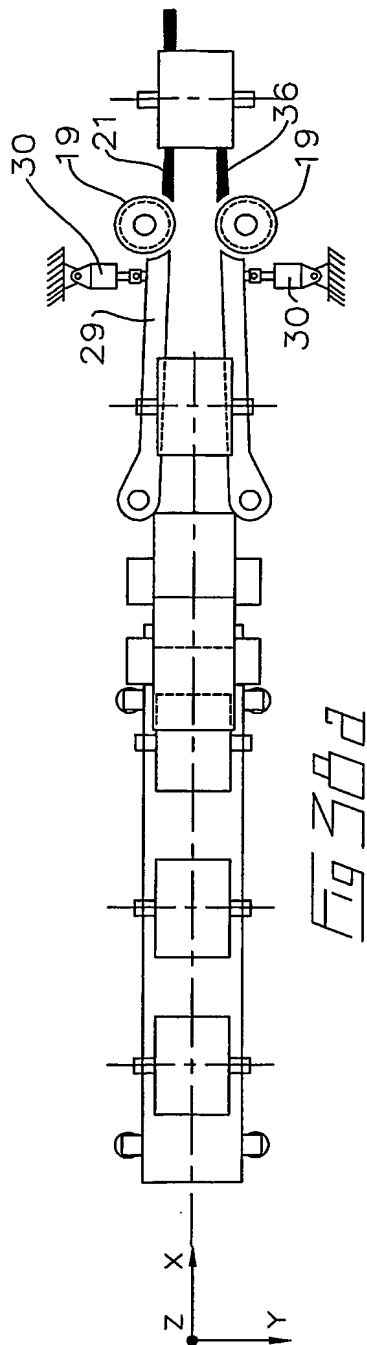
Fig 36

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EXAMPLE OF OPTIMIZED PLANING OF A WORK PIECE WITH WANE DEFECTS

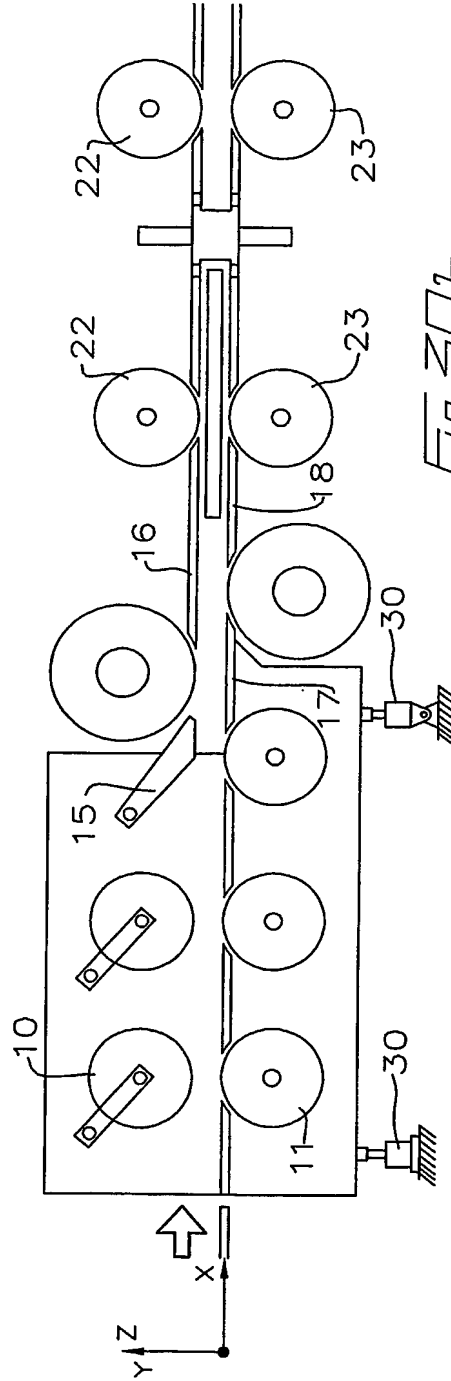
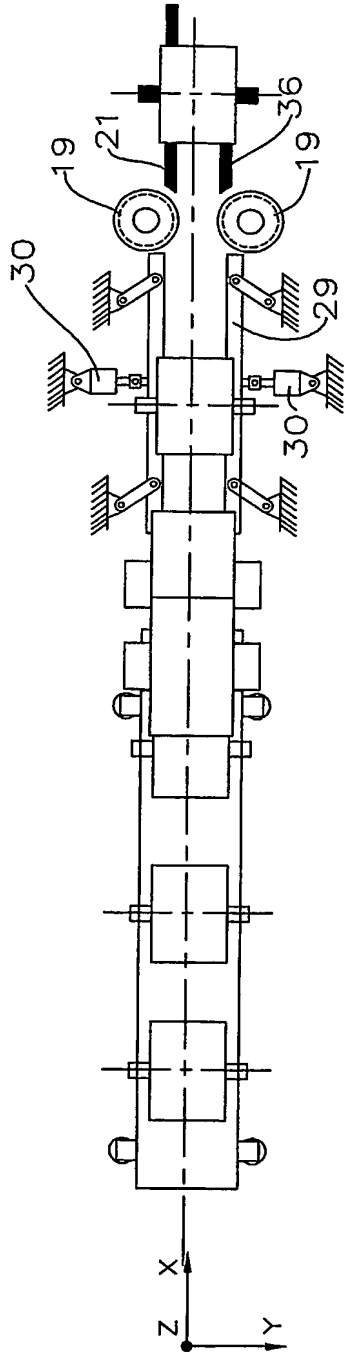
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OPTIMIZING PLANNER-THREE AXIS INFEED POSITIONING MODULE WITH INTERMEDIATE SIDE HEAD STEERING

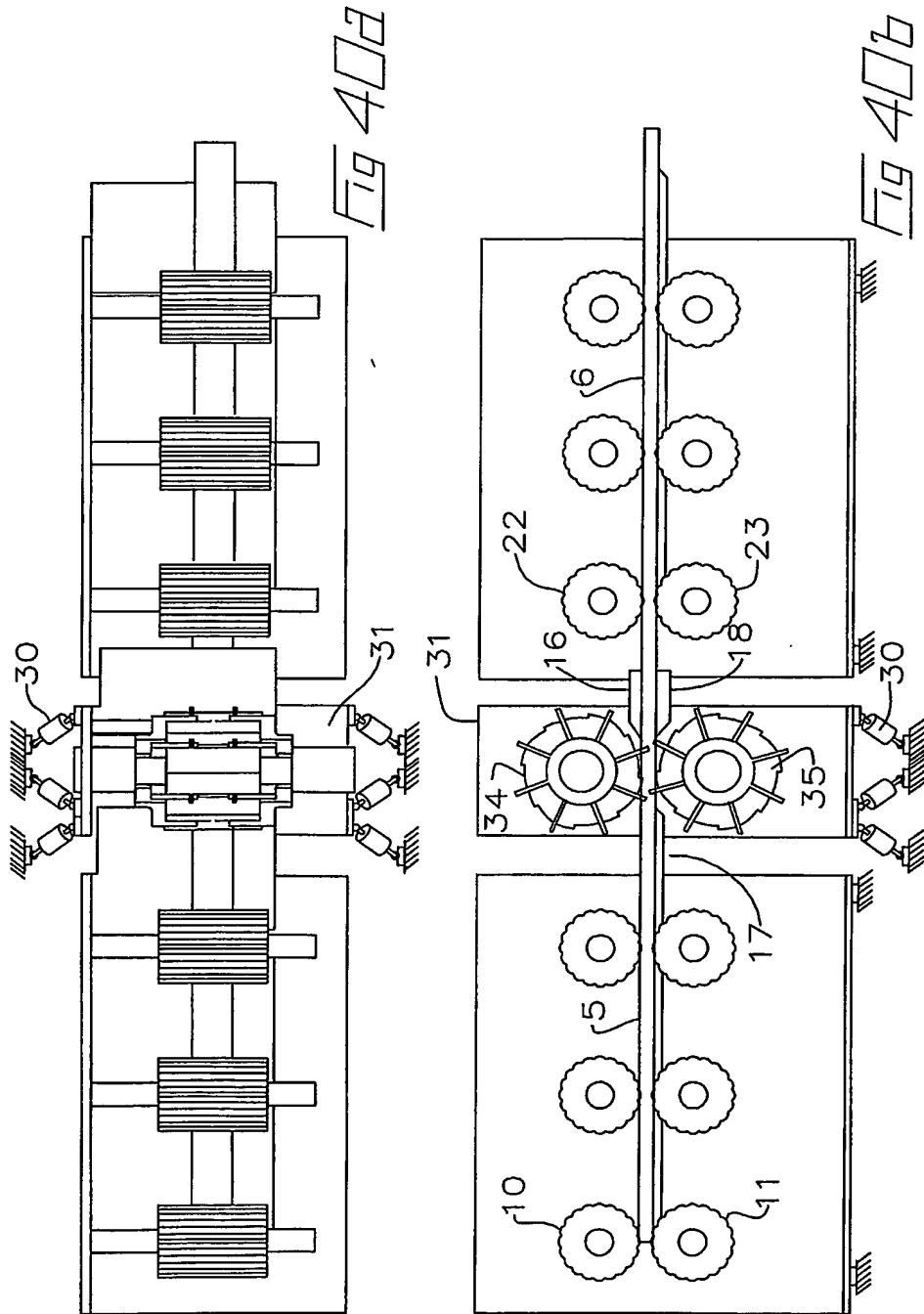


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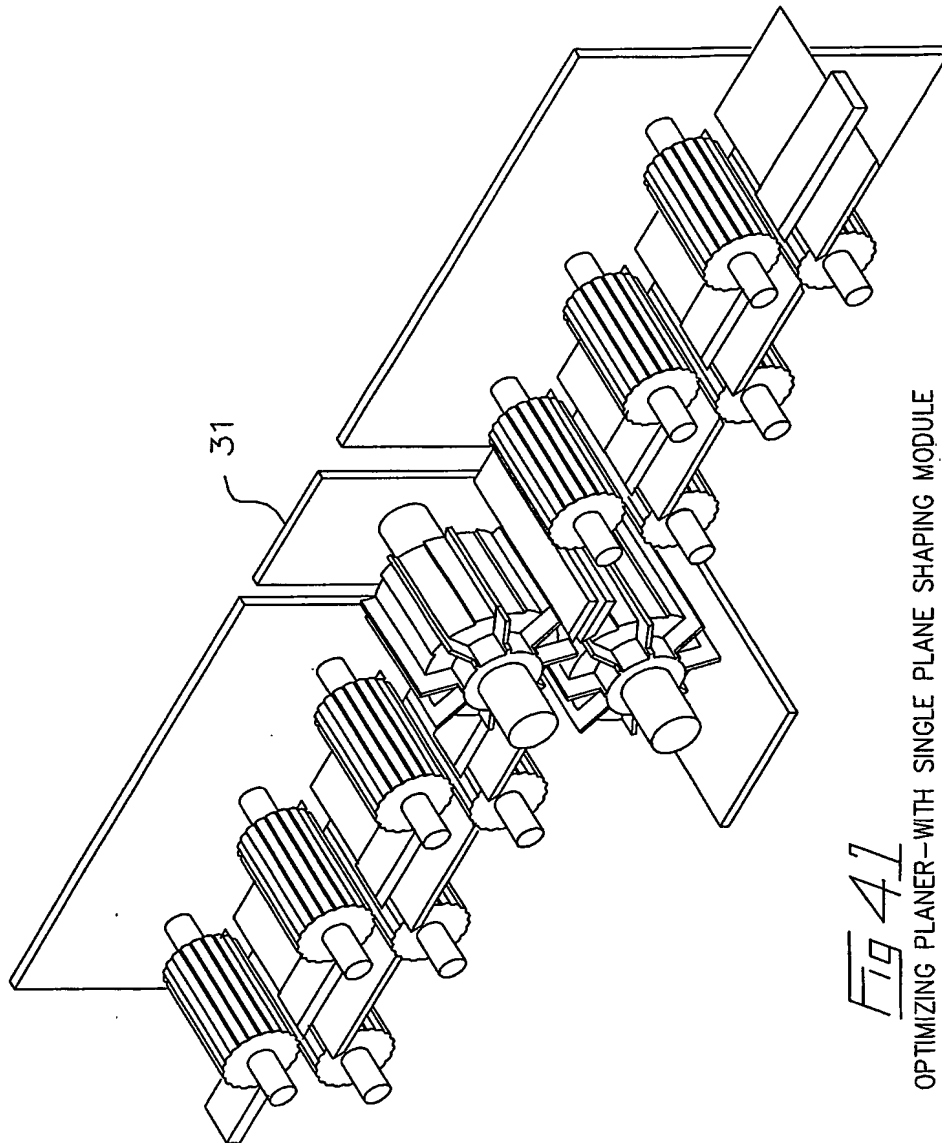
OPTIMIZING PLANNER-THREE AXIS INFED POSITIONING MODULE WITH PARALLEL INTERMEDIATE SIDE HEAD STEERING

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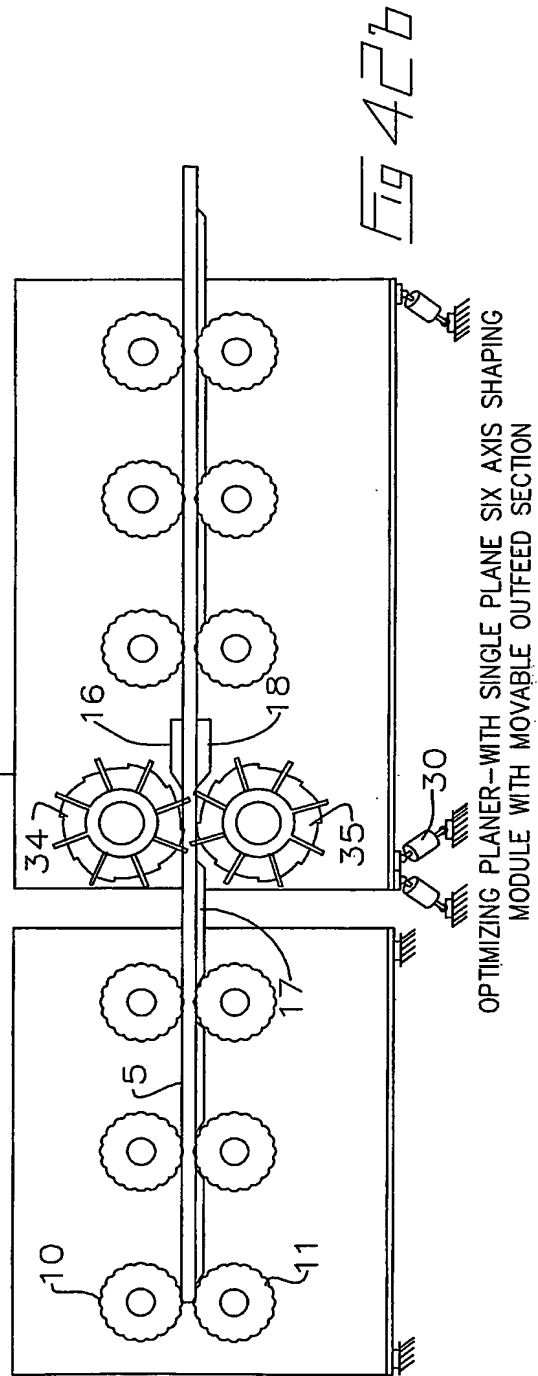
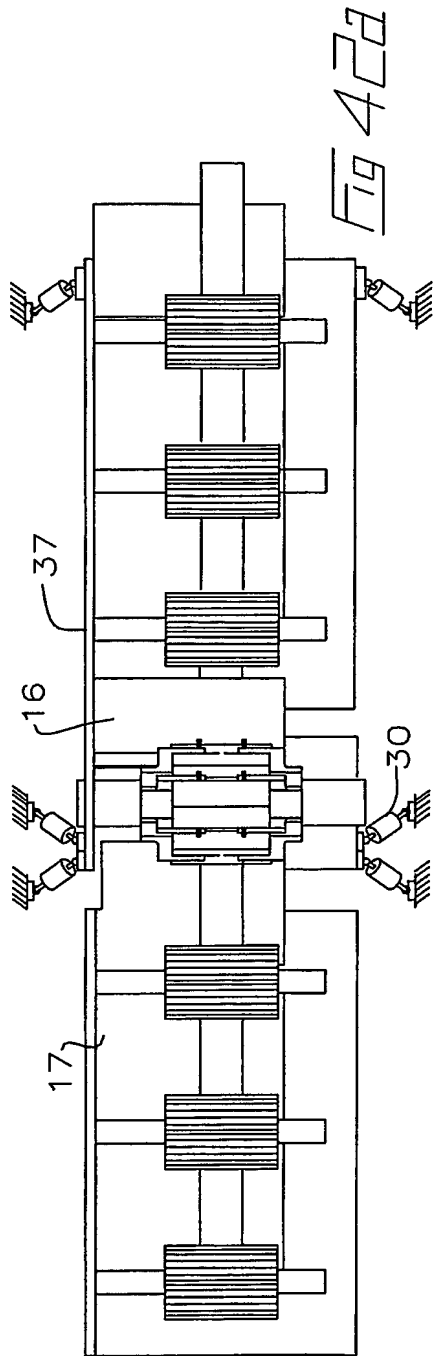


OPTIMIZING PLANER—WITH SINGLE PLANE SIX AXIS SHAPING MODULE

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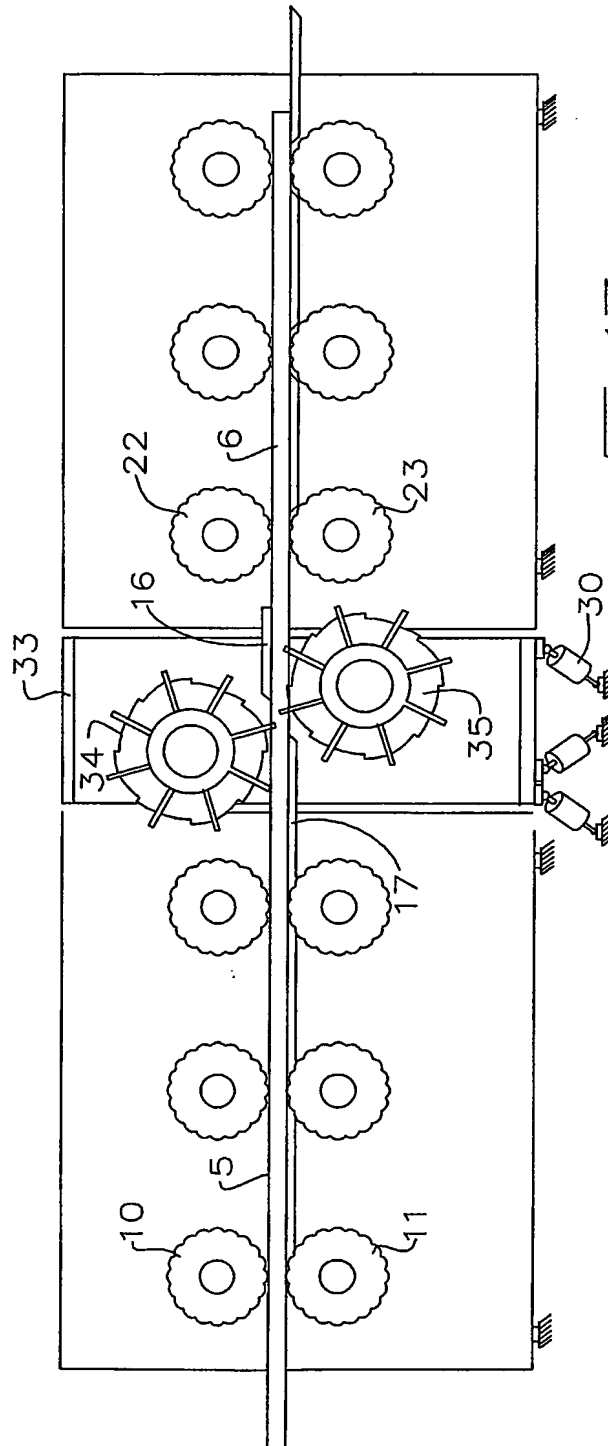


Fig 43

OPTIMIZING PLANER- WITH OFFSET PLANER HEAD SIX AXIS SHAPING MODULE

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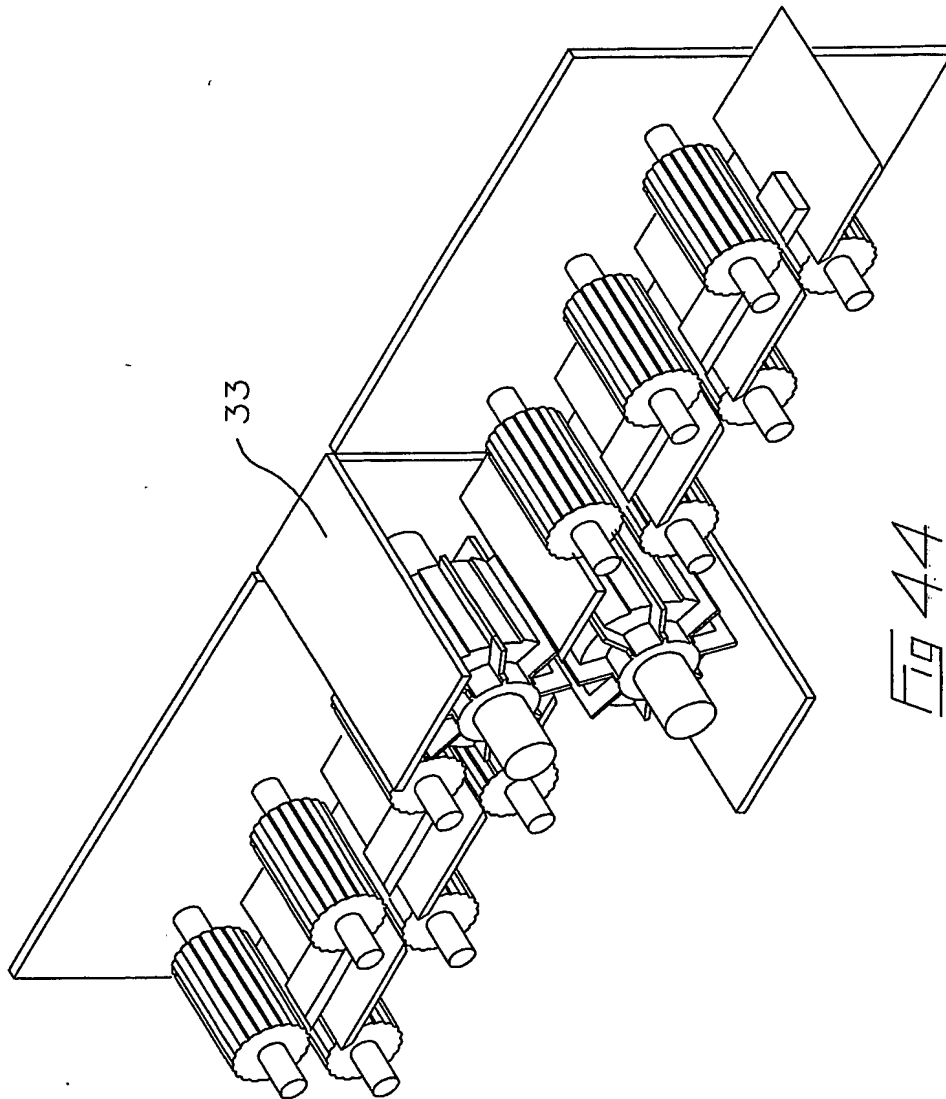
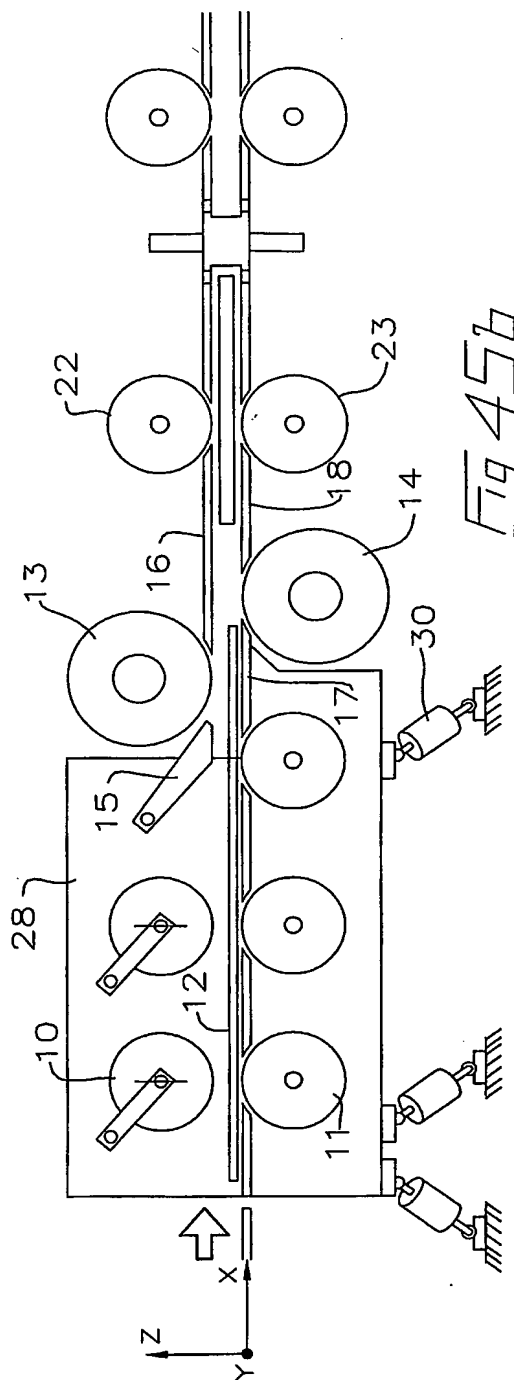
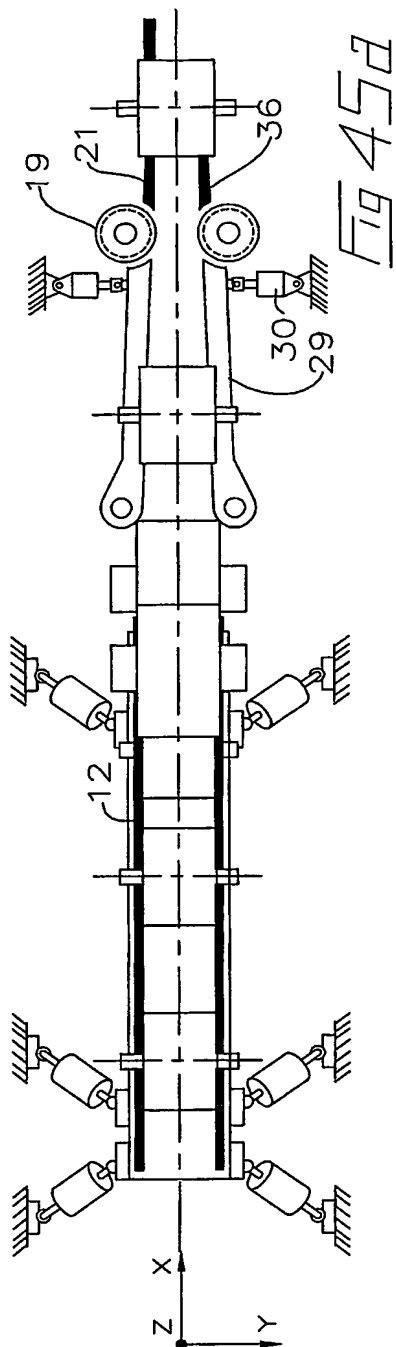


Fig 44

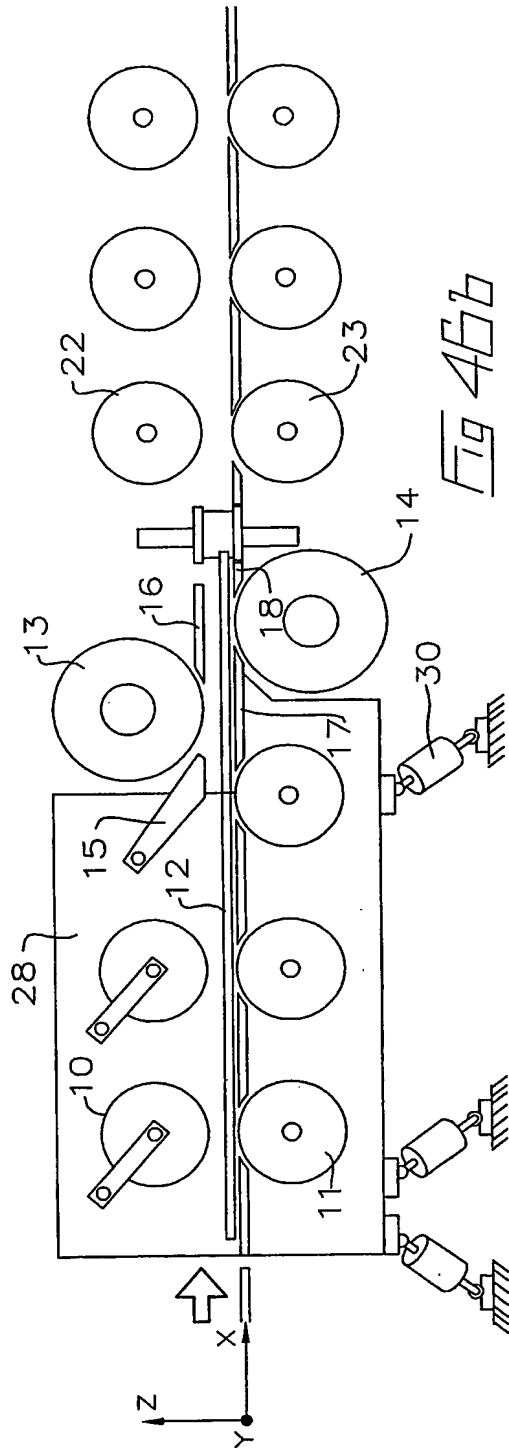
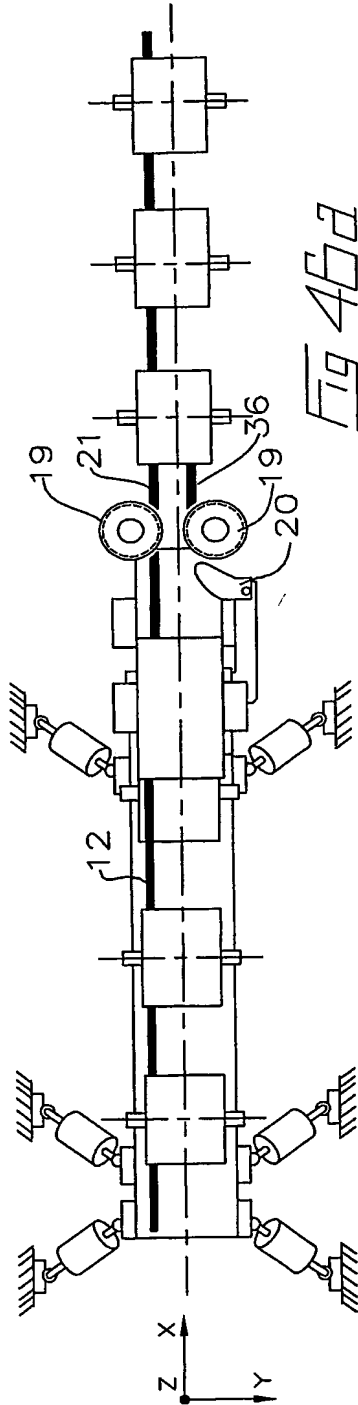
OPTIMIZING PLANER—WITH OFFSET PLANER HEAD SIX AXIS SHAPING MODULE

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OPTIMIZING PLANNER WITH SIX AXIS INFED POSITIONING MODULE AND INTERMEDIATE SIDE STEERING MODULE

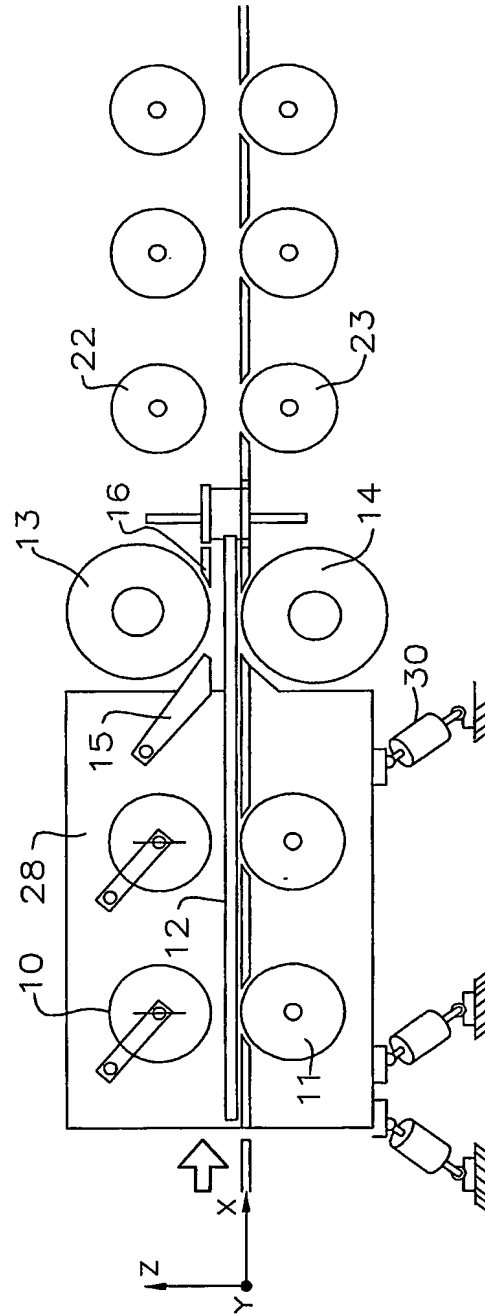
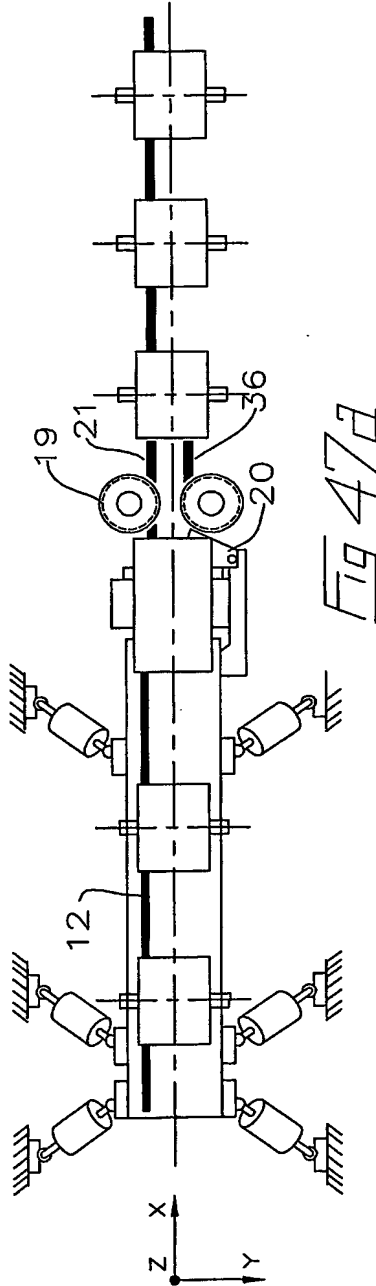
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OPTIMIZING PLANER WITH SIX AXIS INFED POSITIONING MODULE(OFFSET TOP AND BOTTOM HEADS)

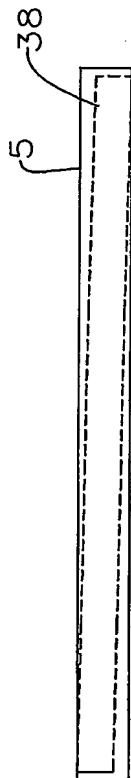


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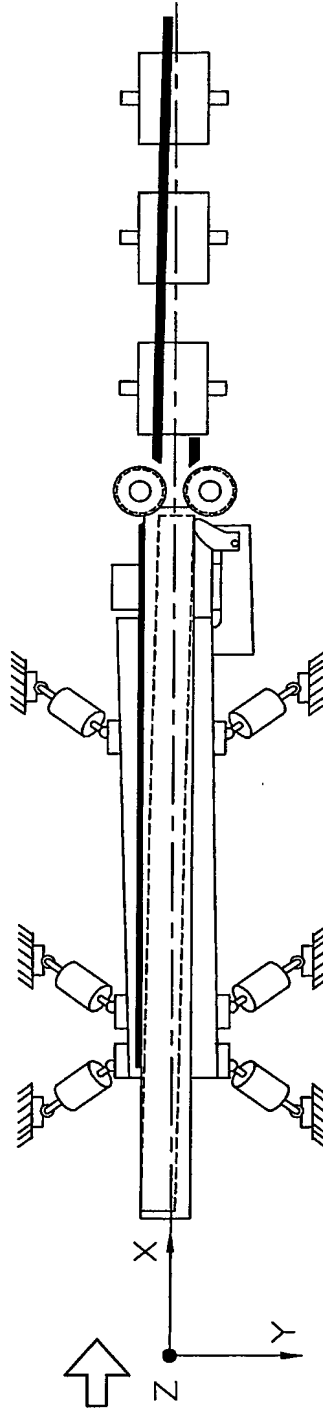


OPTIMIZING PLANNER WITH SIX AXIS INFEEED POSITIONING MODULE (INLINE TOP AND BOTTOM HEADS)

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*Fig 40a*  
TOP VIEW OF ROUGH WORK PIECE



*Fig 40*  
OPTIMIZED PLANER-FEEDING EXAMPLE(TOP VIEW)

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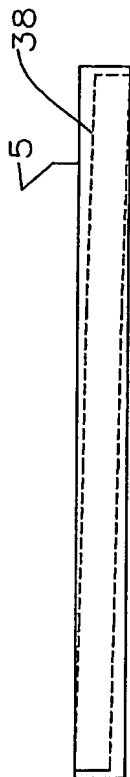


Fig 49a

SIDE VIEW OF ROUGH WORK PIECE

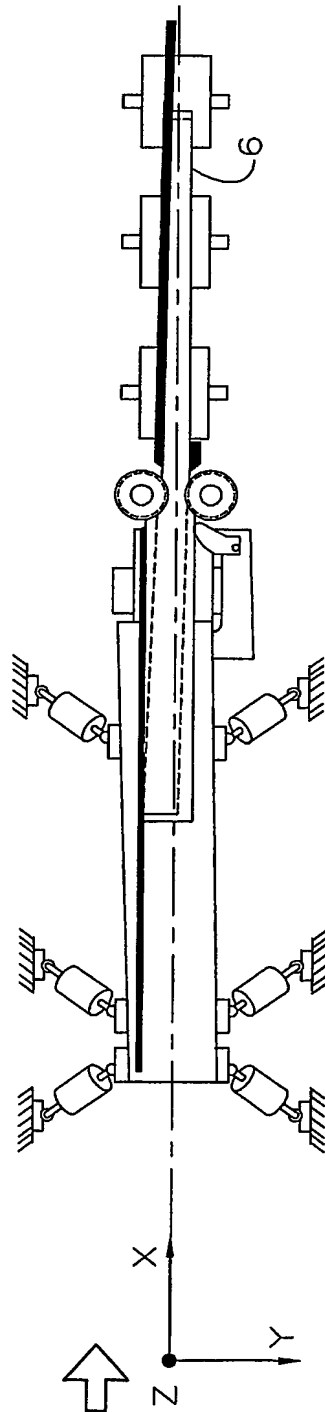
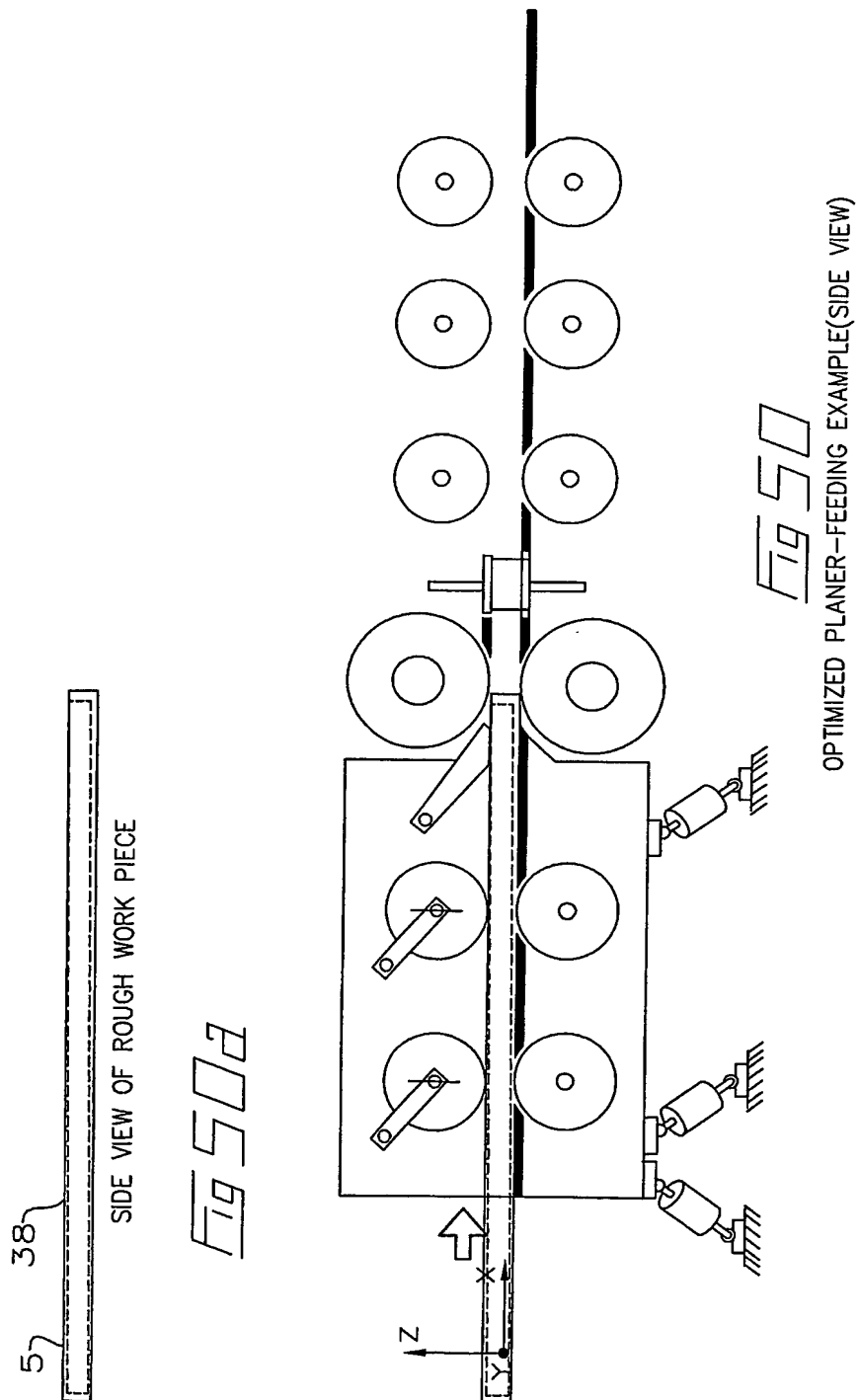
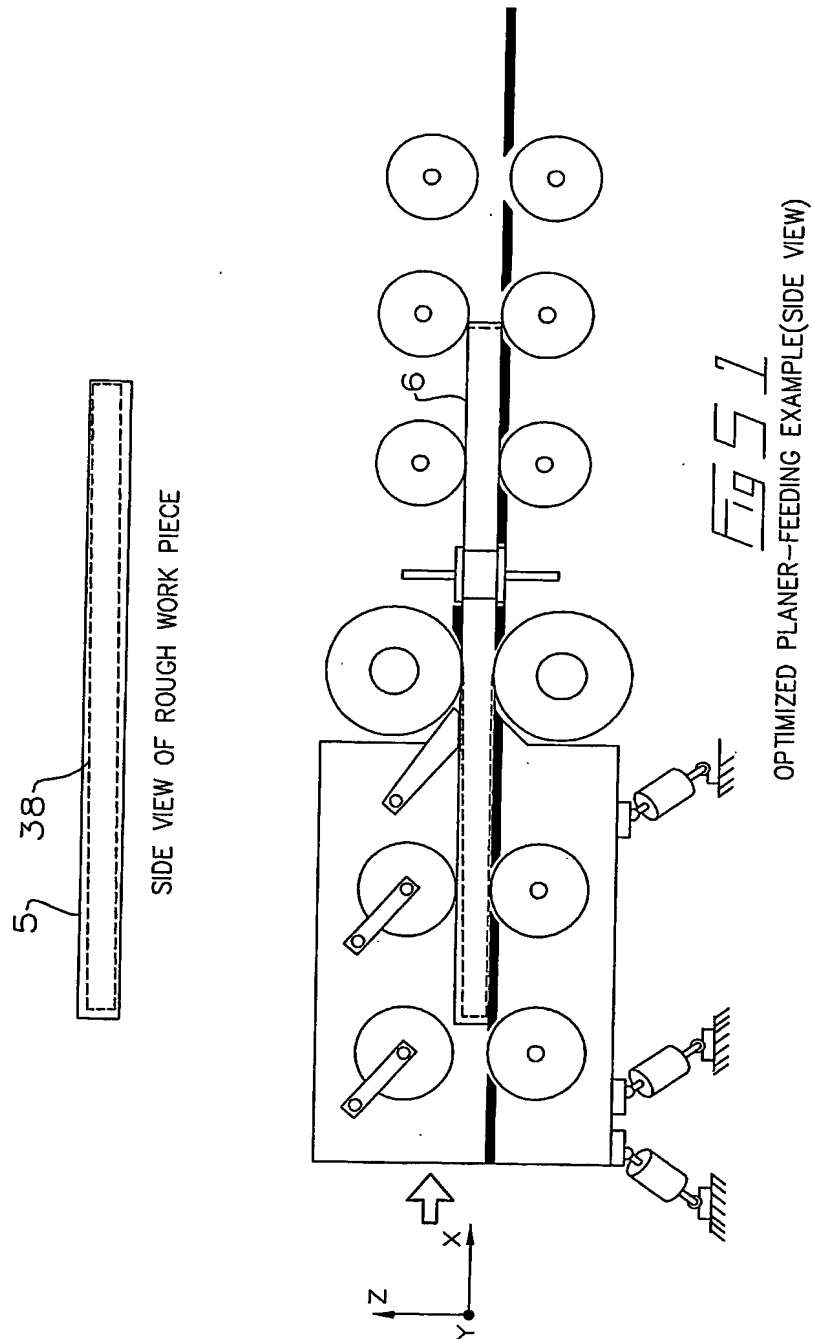


Fig 49

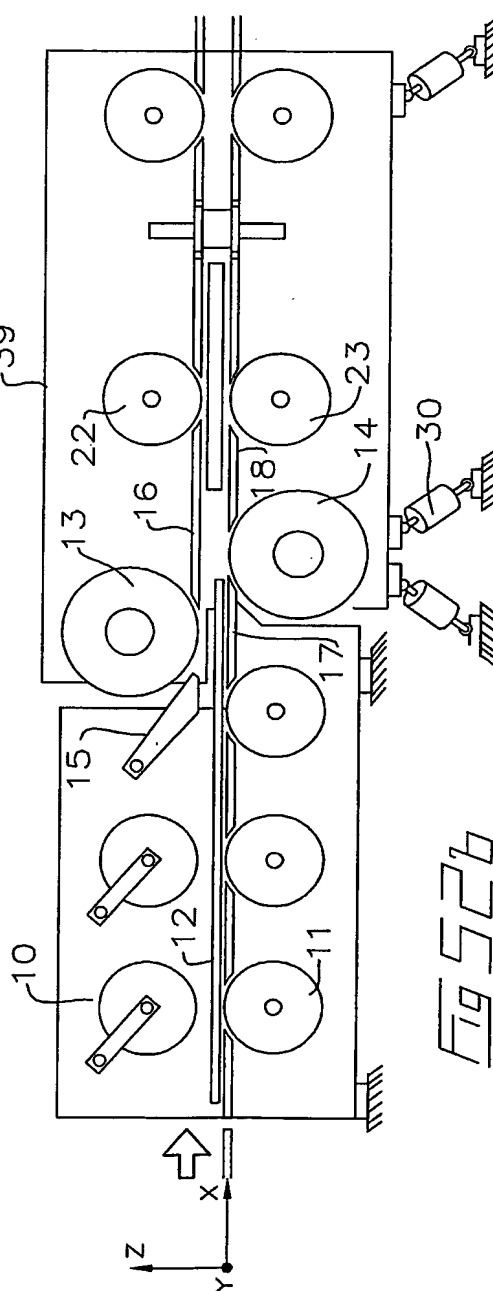
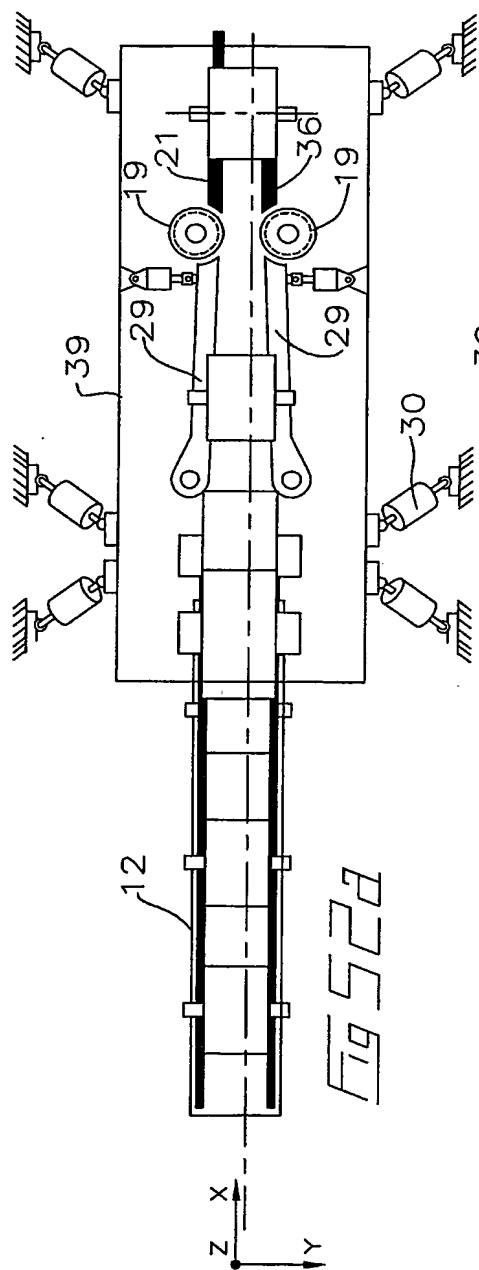
OPTIMIZED PLANER-FEEDING EXAMPLE(TOP VIEW)



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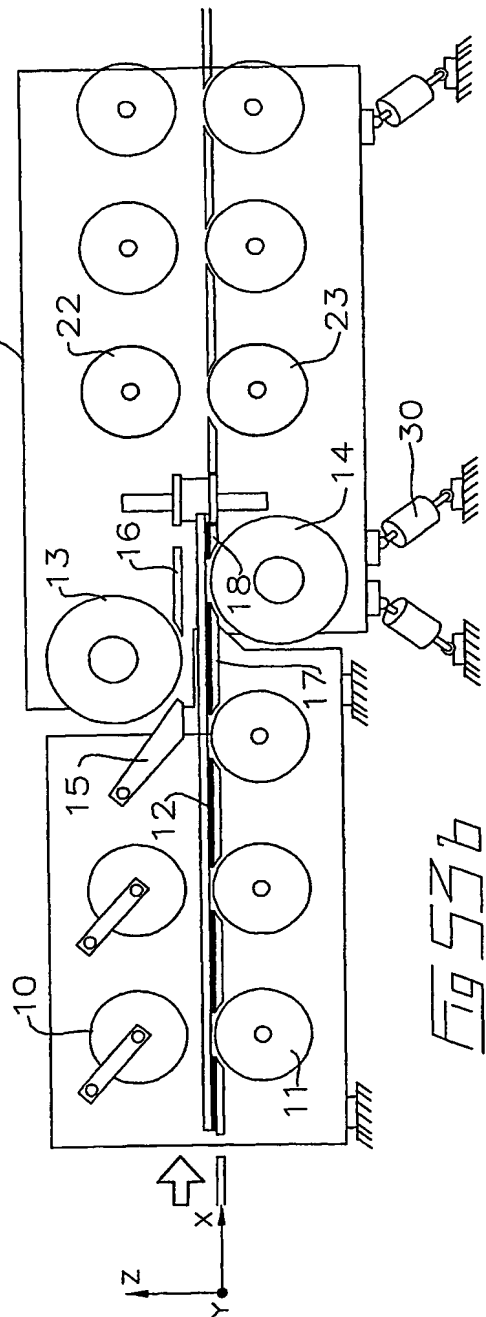
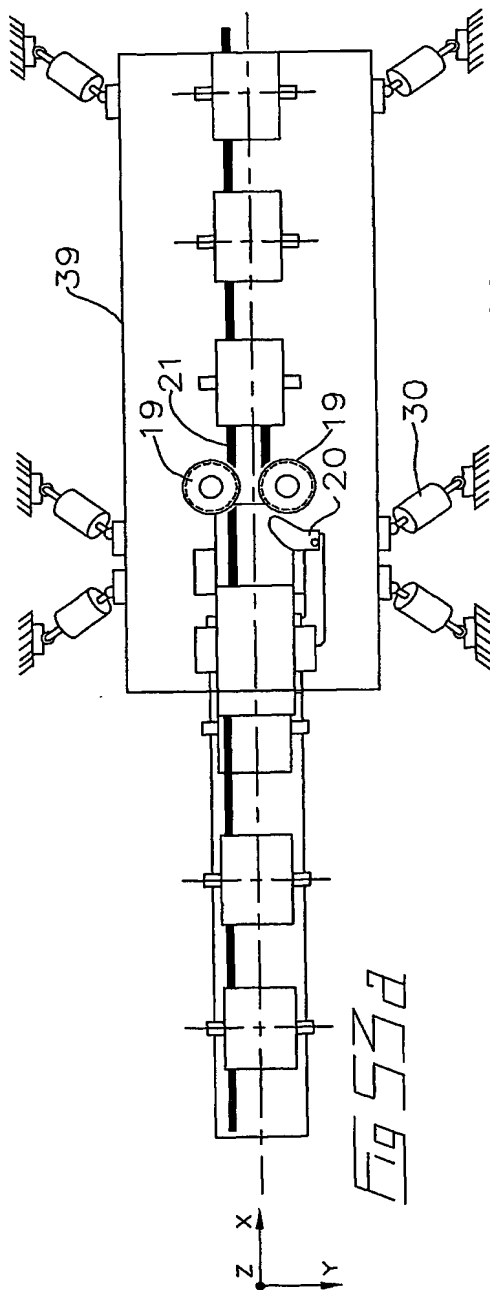


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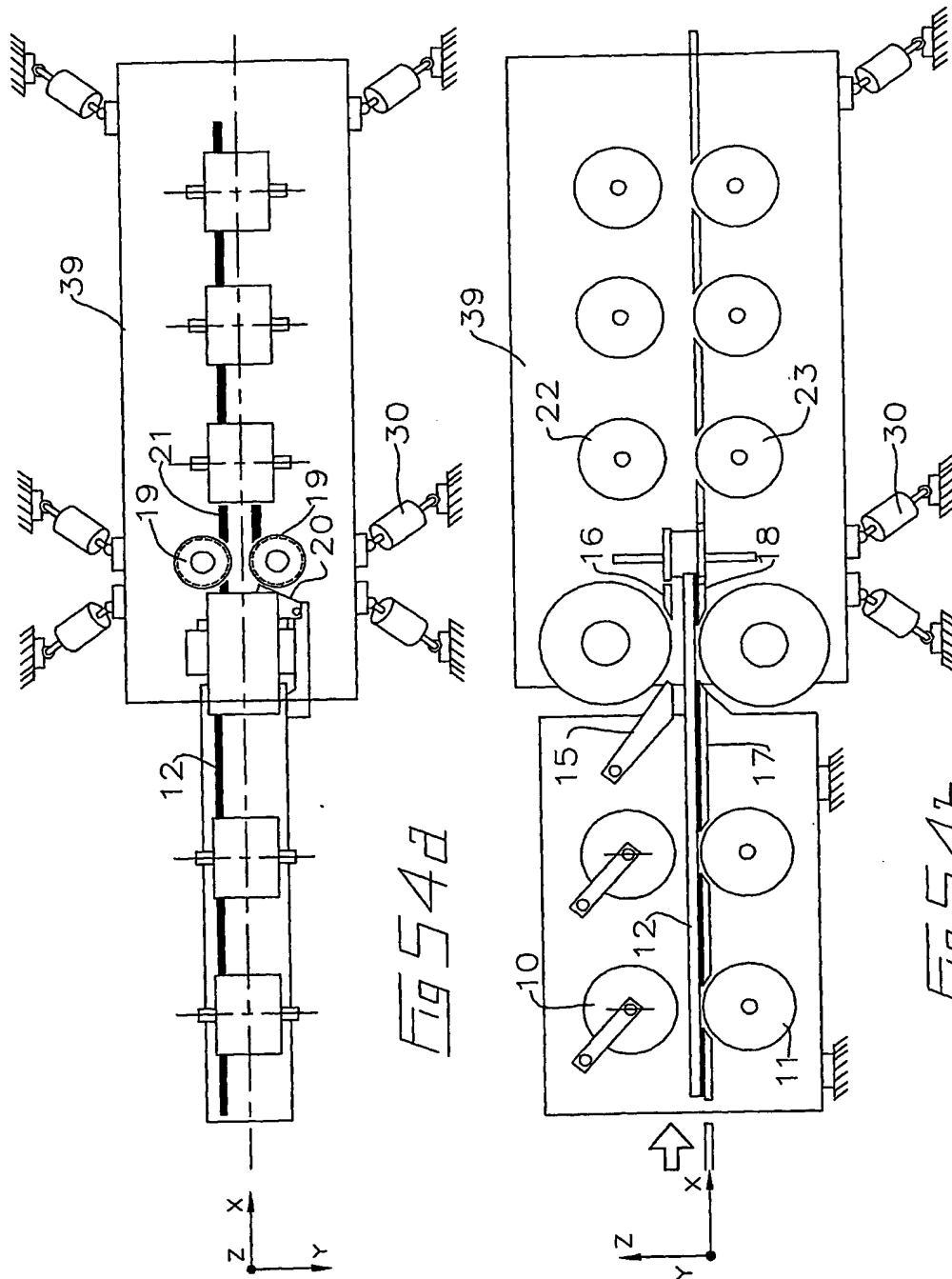
OPTIMIZING PLANER WITH SIX AXIS OUTFEED POSITIONING MODULE AND INTERMEDIATE SIDE STEERING MODULE

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OPTIMIZING PLANER WITH SIX AXIS OUTFEED POSITIONING MODULE WITH OFFSET MAIN PLANER HEADS

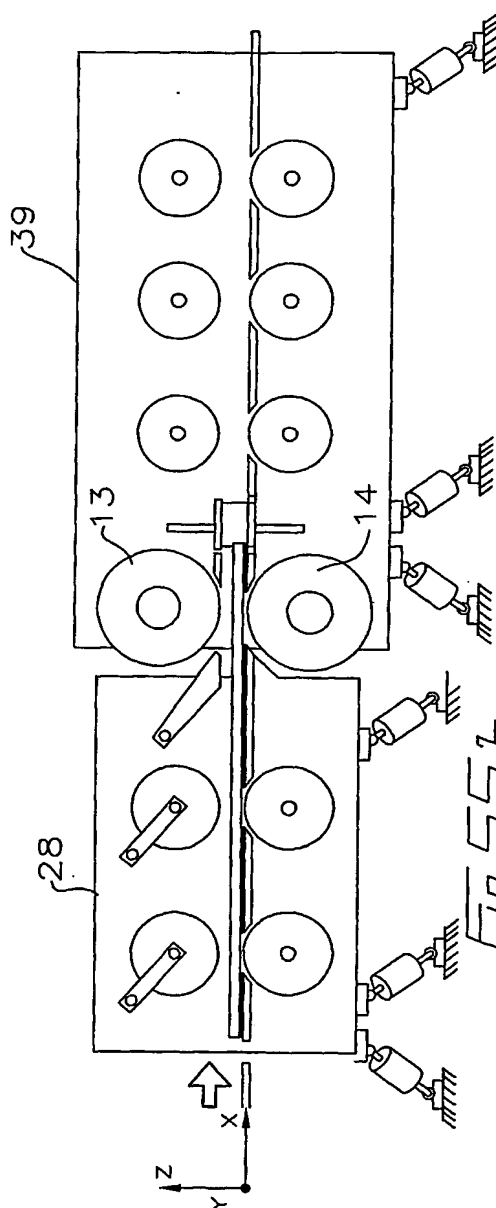
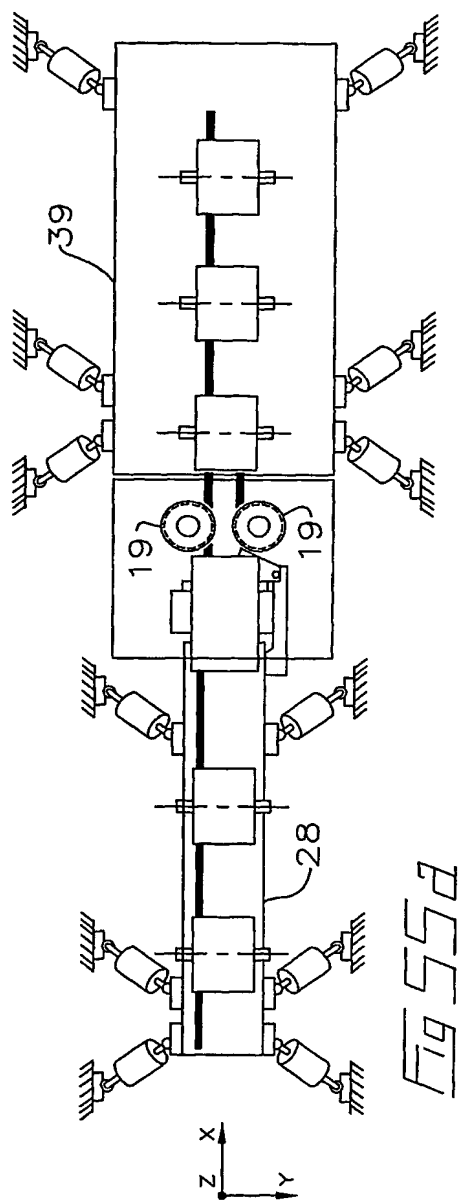
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OPTIMIZING PLANER WITH SIX AXIS OUTFEED POSITIONING MODULE WITH INLINE MAIN PLANER HEADS

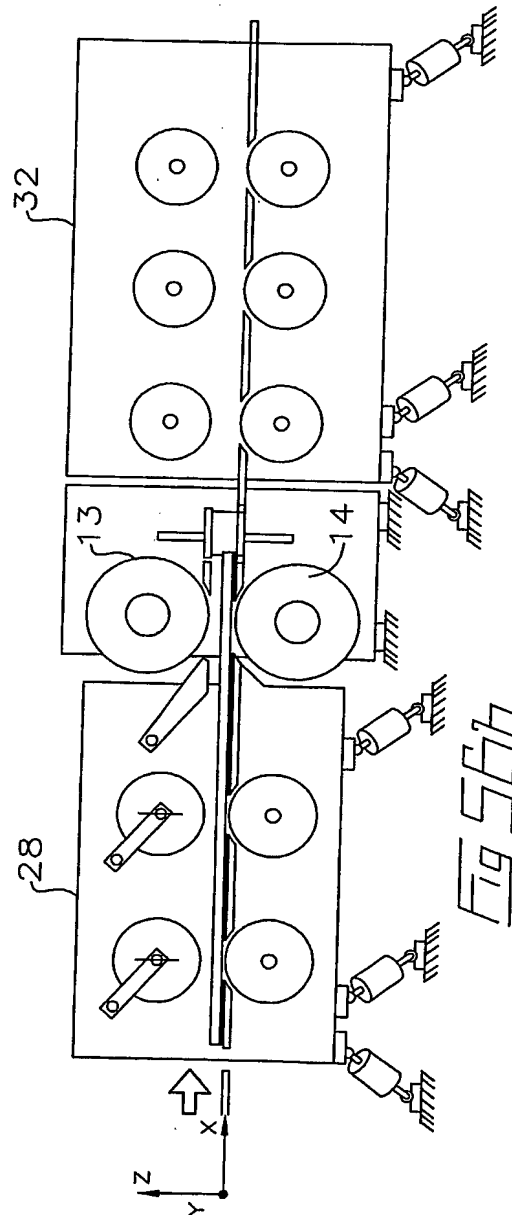
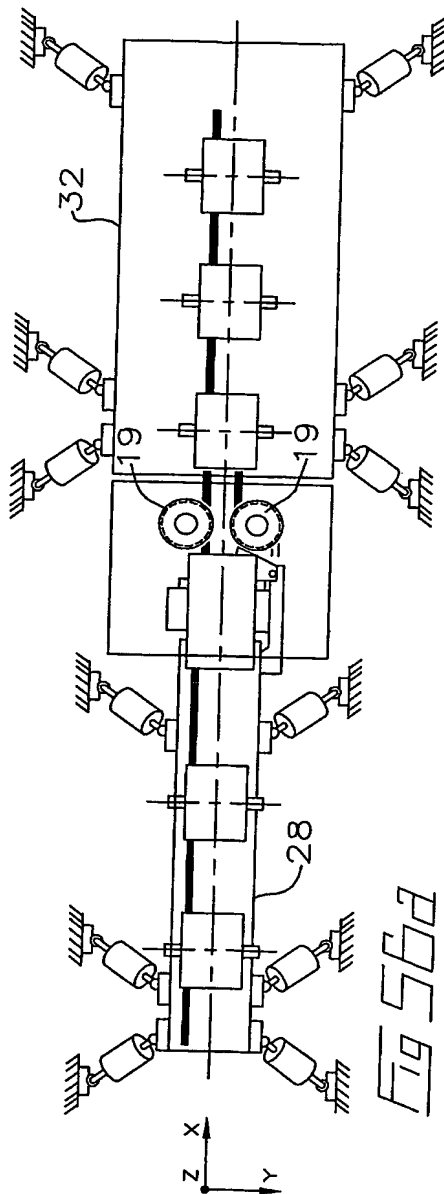


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OPTIMIZING PLANNER WITH SIX AXIS INFED AND OUTFEED POSITIONING MODULES (HEADS MOVING WITH OUTFEED)

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OPTIMIZING PLANNER WITH SIX AXIS INFED AND OUTFEED POSITIONING MODULES (STATIONARY HEADS)

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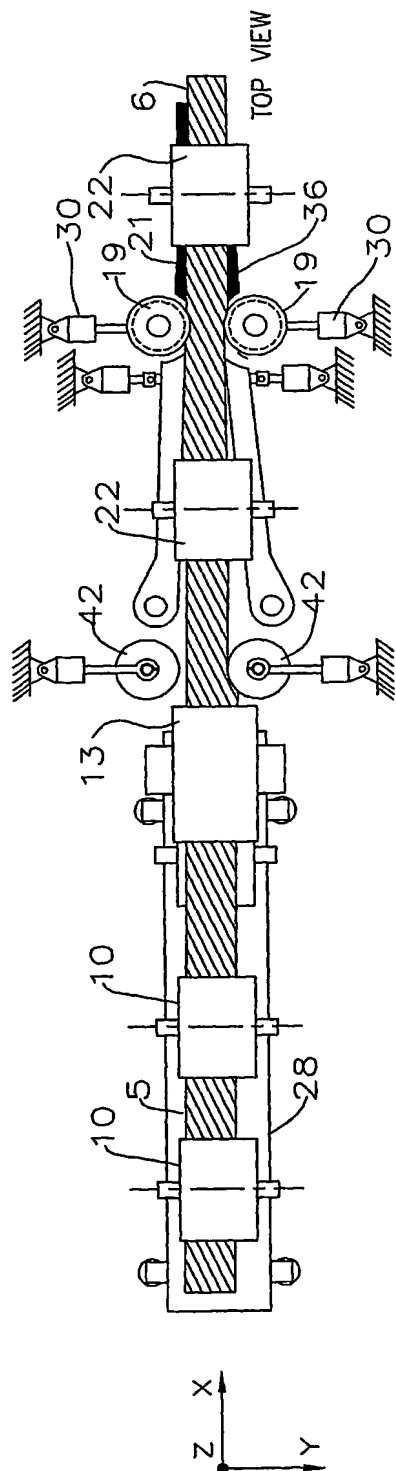


Fig 57  
OPTIMIZING PLANER—OPTIONAL SIDE PRE-CUT  
(TO REDUCE WORK PIECE TO A SMALLER NOMINAL SIZE)

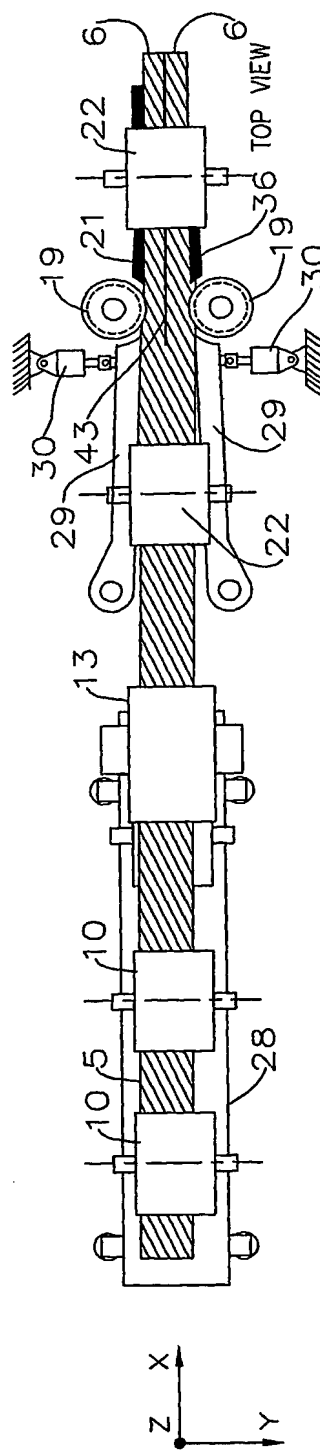


Fig 58  
OPTIMIZING PLANER—OPTIONAL INTERIOR PROFILING  
(TO SPLIT SINGLE WORK PIECE INTO TWO PIECES)

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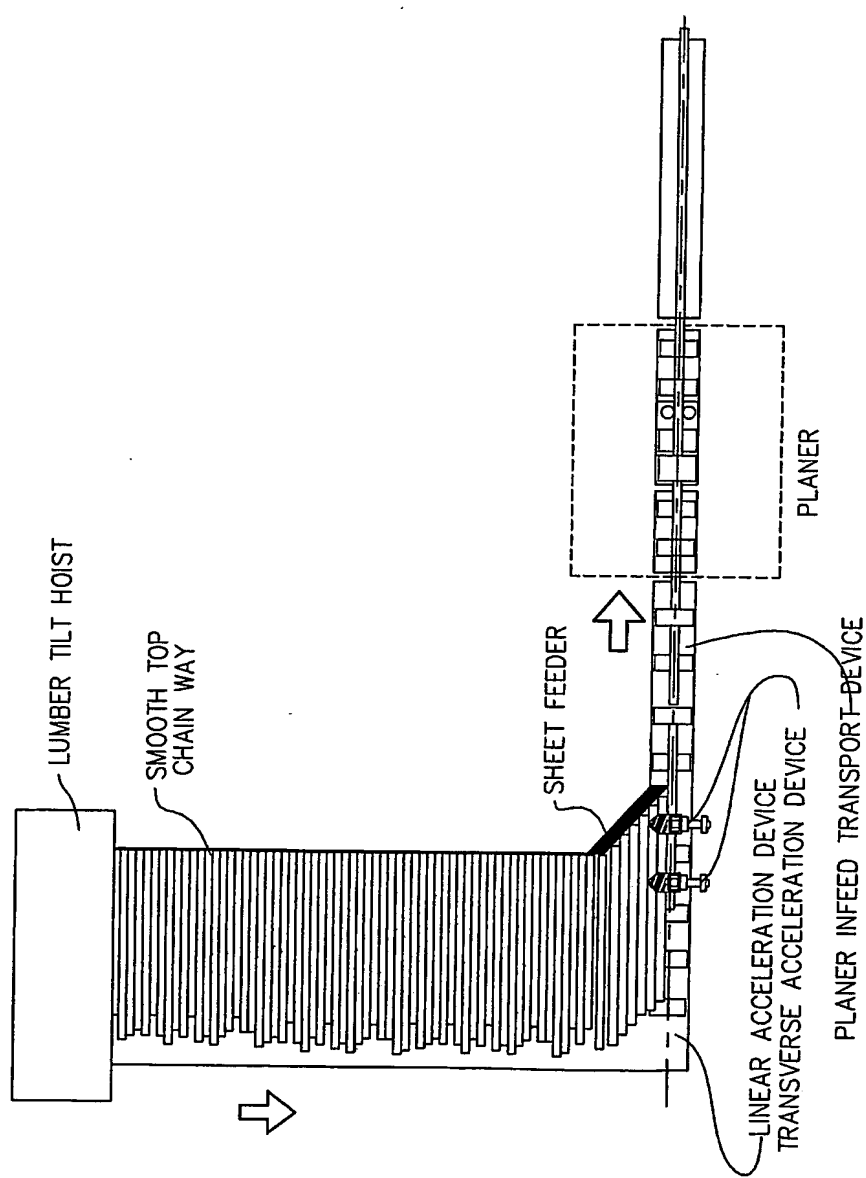


Fig 59

CONVENTIONAL PLANER INFED SYSTEM--SHORT INFED TRANSPORT DEVICE  
(BEFORE CONVERSION TO OPTIMIZED SYSTEM)

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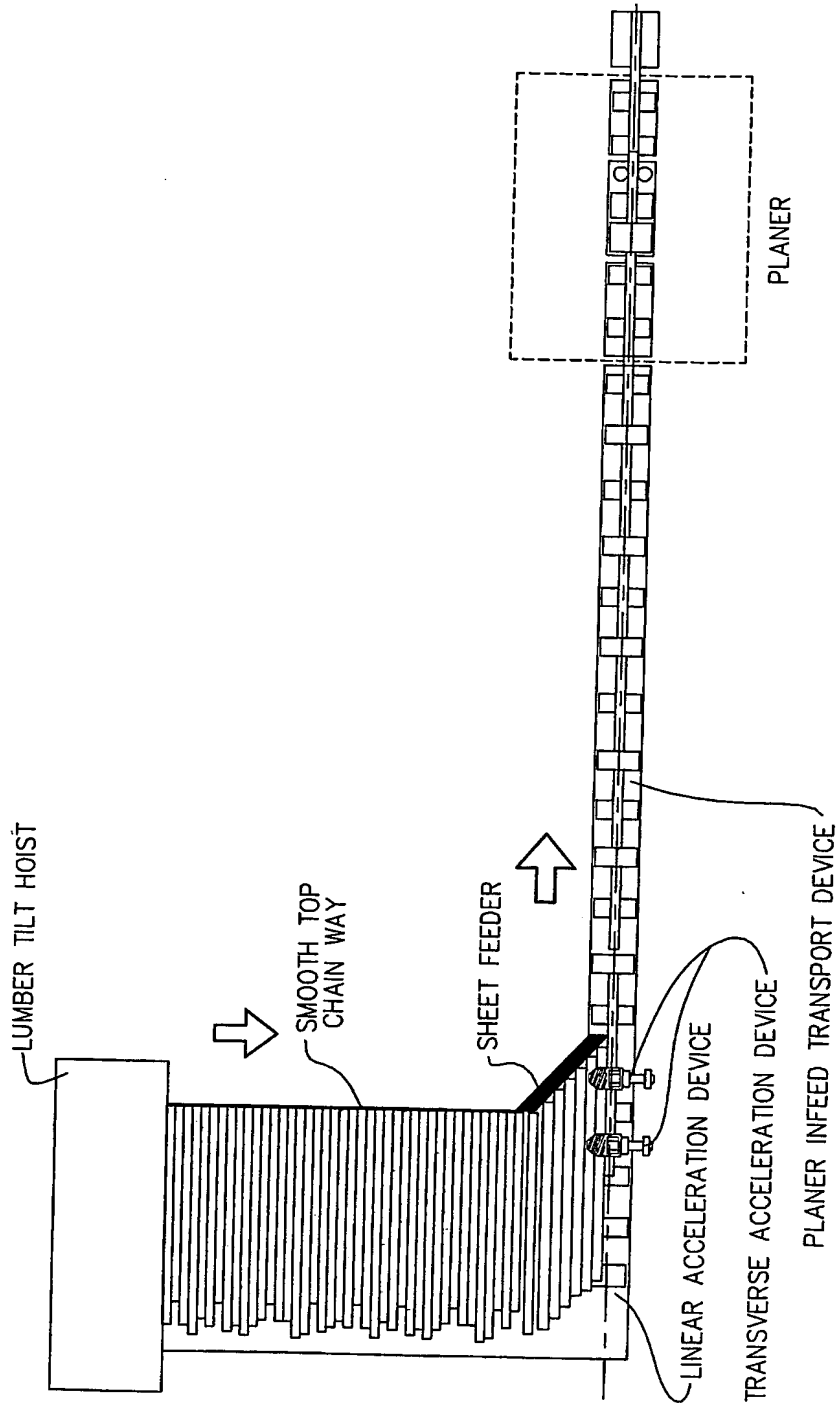


Fig 60

CONVENTIONAL PLANER INFED SYSTEM—LONG INFED TRANSPORT DEVICE  
(BEFORE CONVERSION TO OPTIMIZED SYSTEM)

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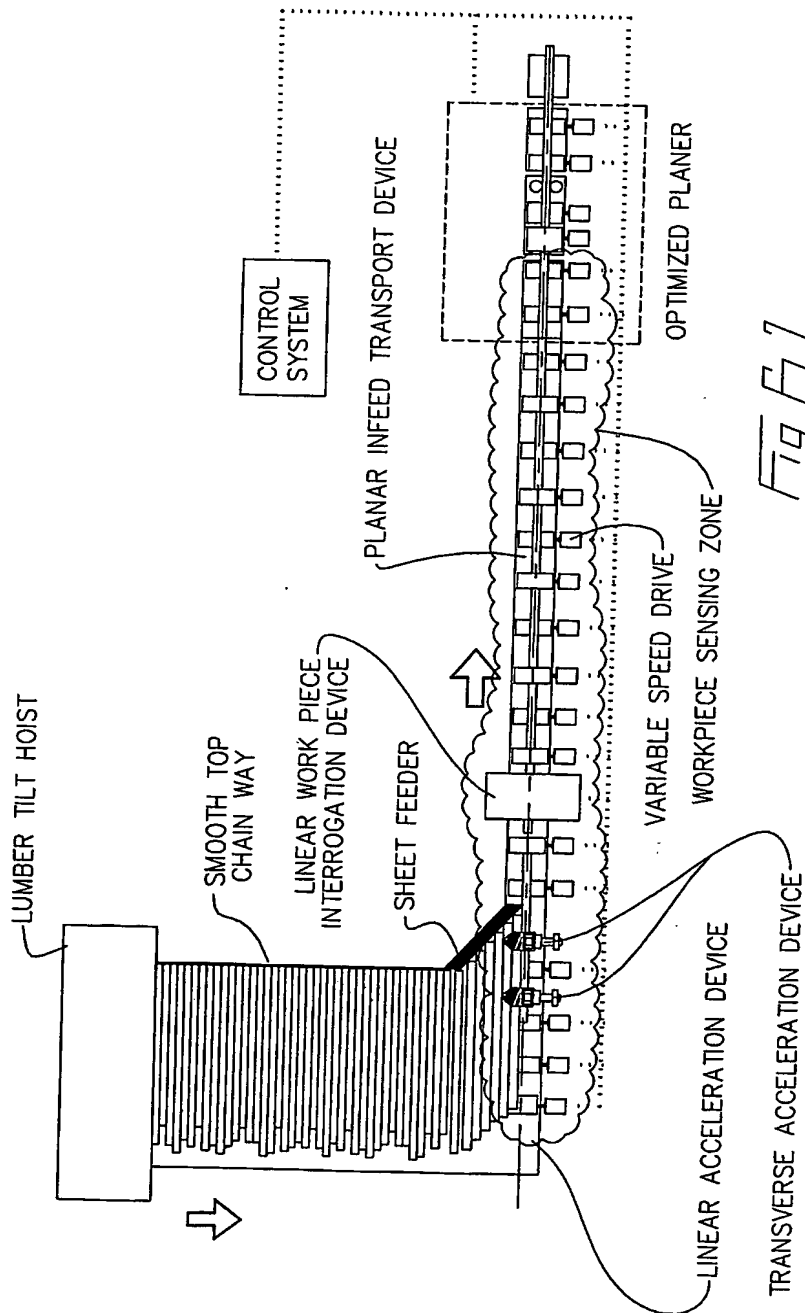


Fig 61

CONVENTIONAL PLANER INFEED SYSTEM—LONG INFEED TRANSPORT DEVICE  
(AFTER CONVERSION TO OPTIMIZED SYSTEM)

